



Surface Acoustic Wave (SAW) Wireless Passive Temperature Sensors

VECTRON International - SenGenuity

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History of Surface Acoustic Wave (SAW)

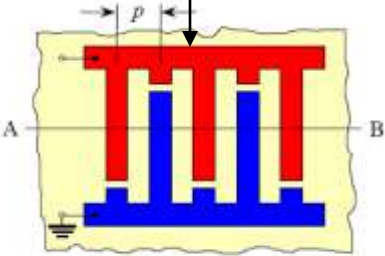
- 1880** Piezoelectricity, discovered by Jacques and Pierre Curie in quartz crystals`
- 1885** Lord Rayleigh characterizes Surface Acoustic Waves (earth quake)
- 1889** First interdigital electrode design, “Electric condenser” U.S. patent Nikole Tesla
- 1965** First Interdigital Transducer (IDT’s) on a polished piezoelectric plate (White / Voltmer)
- 1970** First applications: pulse expansion and compression in radar systems
- 1985** SAW filters replace LC filter in TVs and VCRs
- 1990** SAW filters allow for miniaturization of mobile phones

Electrical power

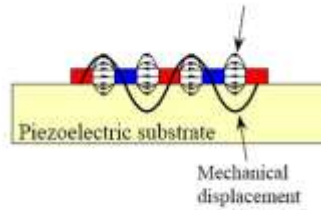
Electric fields lines

Wave propagation ≈ 3000 [m/s]

Rayleigh wave



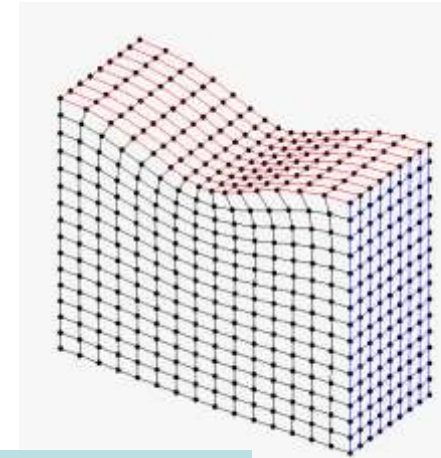
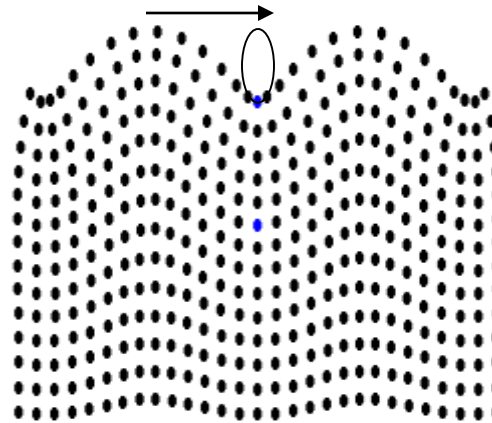
Top view



Cross sectional view A-B

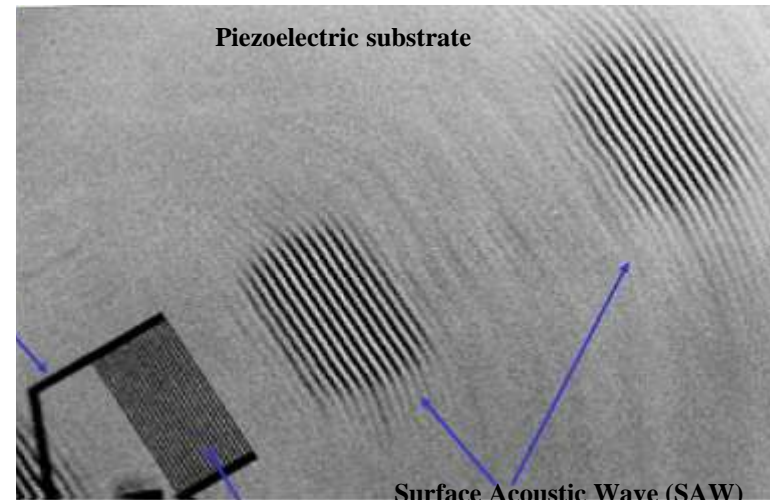
Interdigital Transducer (IDT) as

- transmitter: converse piezoelectric effect \Rightarrow electric RF field generates SAW
 - receiver: piezoelectric effect \Rightarrow SAW generates electric RF field
- In both cases maximum coupling strength for $\lambda_{SAW} = v_{SAW} / f = 2 \cdot p$ ($\sim 1 \dots 10 \mu\text{m}$)



SAW - Rayleigh Wave propagation

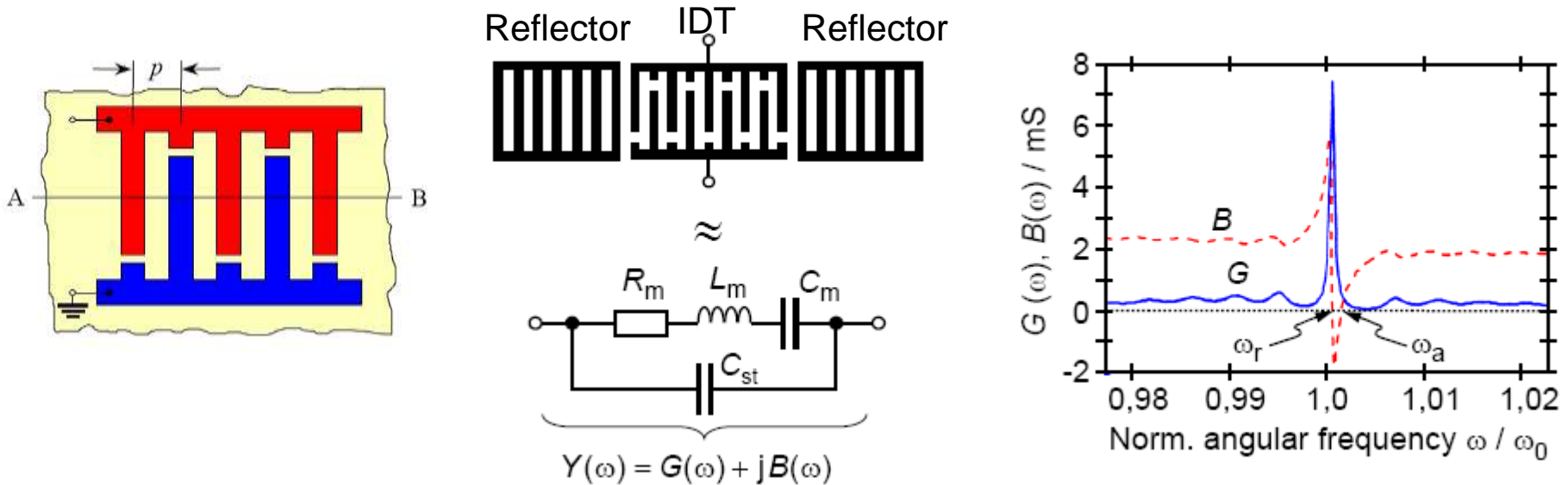
Bus bar



Piezoelectric substrate

IDT

Surface Acoustic Wave (SAW)



First Fact:

Surface wave velocities are temperature dependent and are determined by the orientation and type of crystalline material used to fabricate the sensor

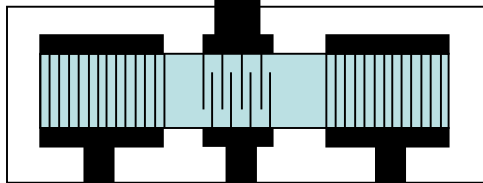
$$v_{SAW} = f_{SAW} \times \lambda \longrightarrow f_{SAW}(T, Cut, \dots)$$

Second Fact:

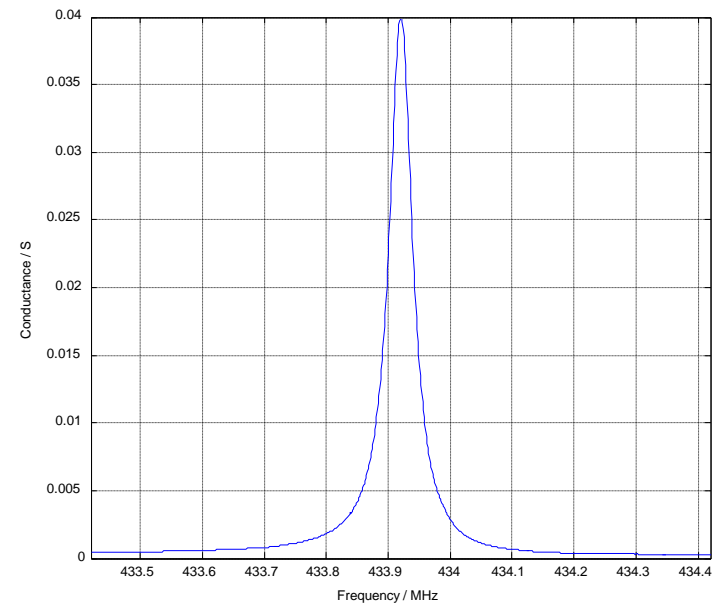
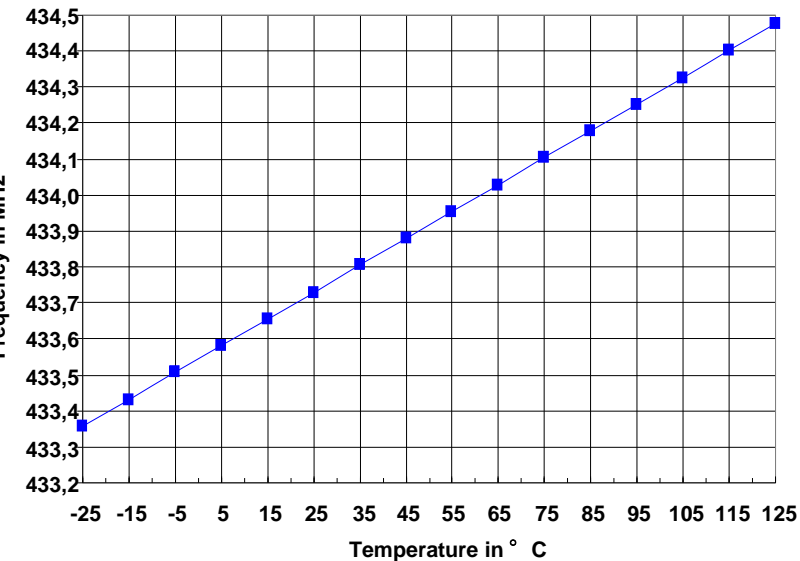
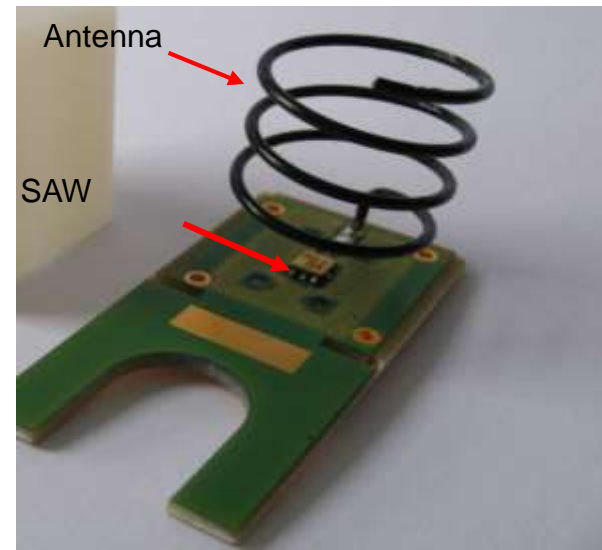
Very low power is required to excite the acoustic wave – Energy Harvesting (EM-Wave)

Single SAW Resonator: Absolute measurement

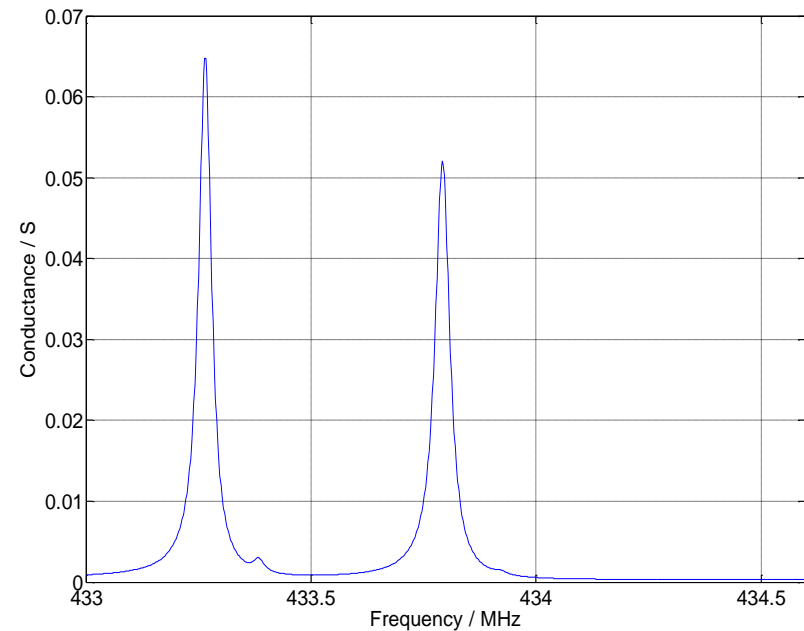
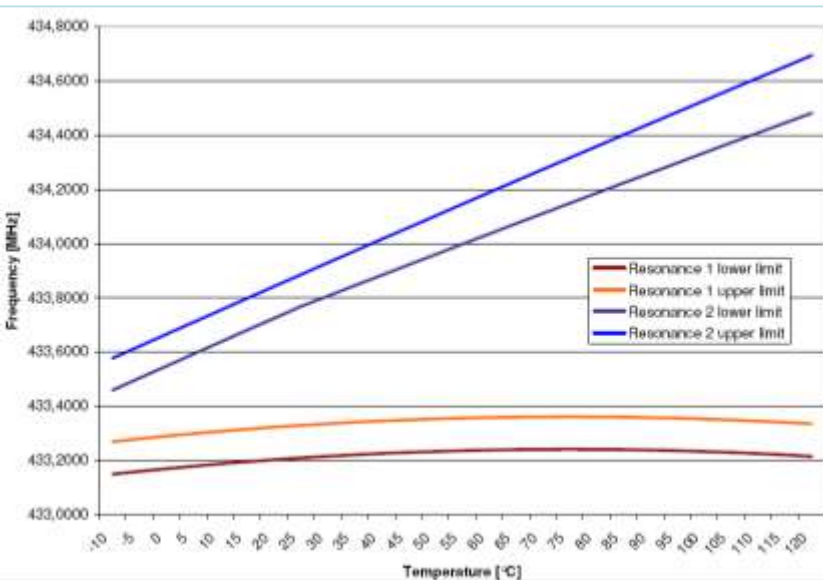
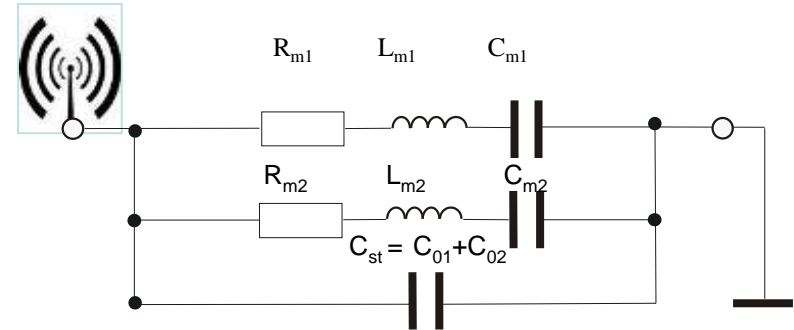
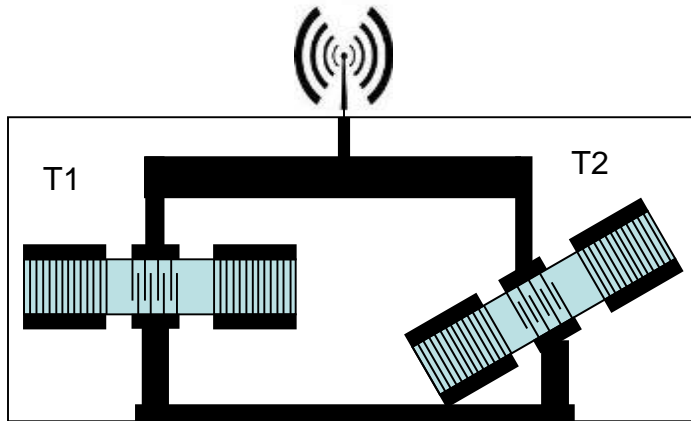
EM -Wave (power)

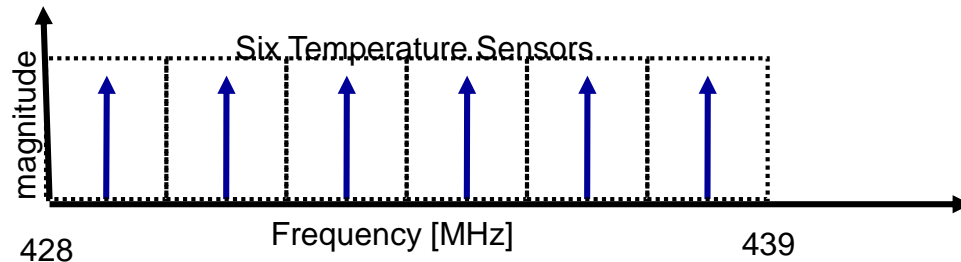


SAW Resonator on
Piezoelectric substrate

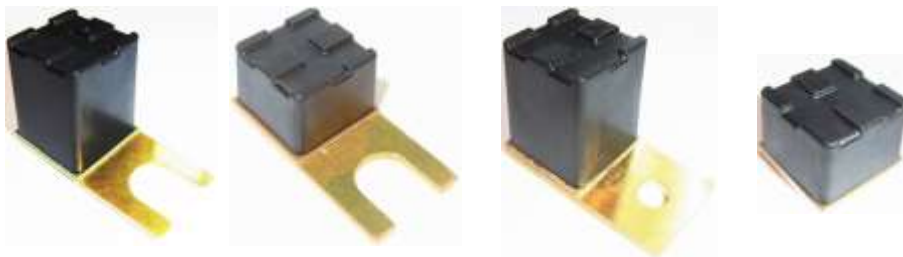


Double SAW Resonator: Differential measurement

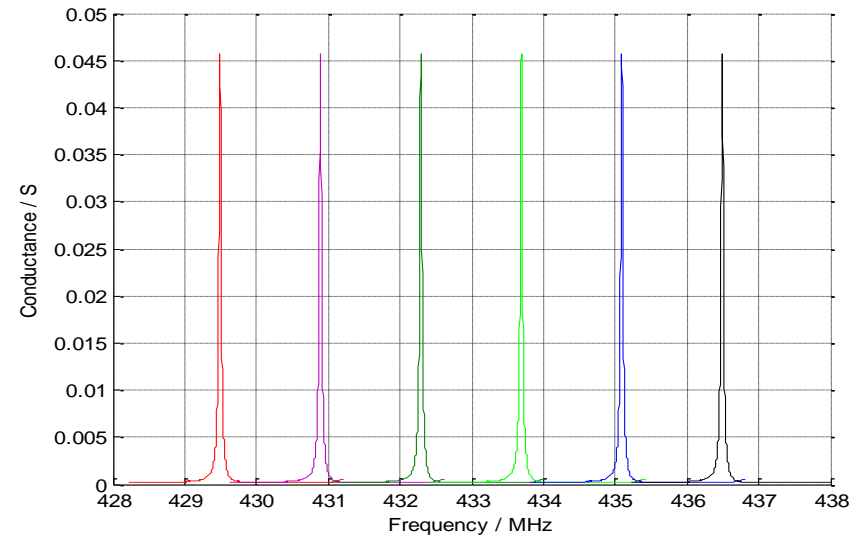
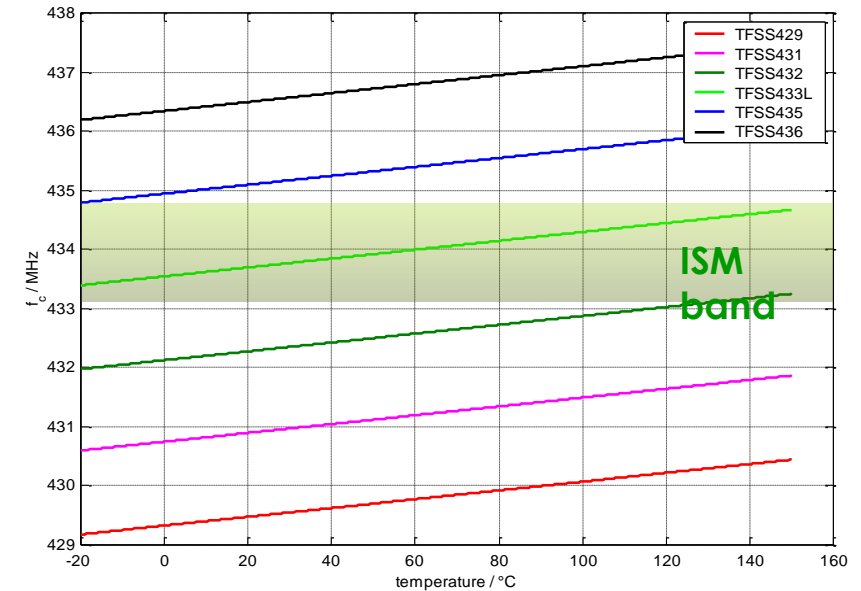


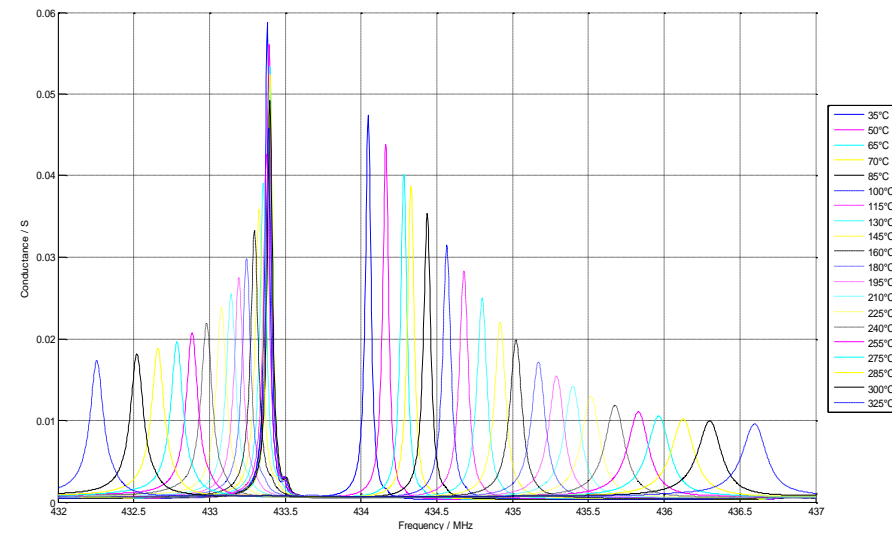
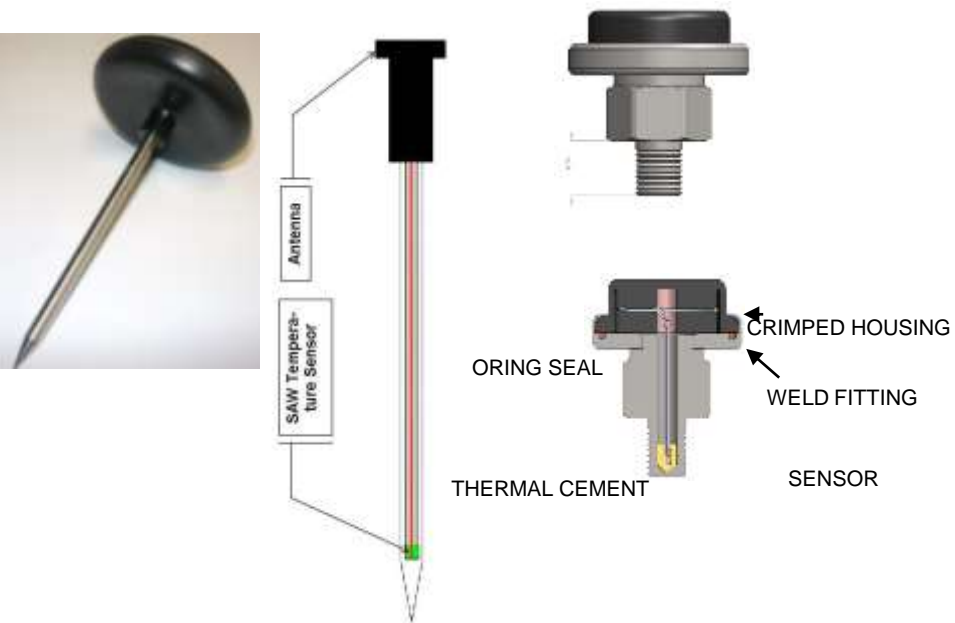
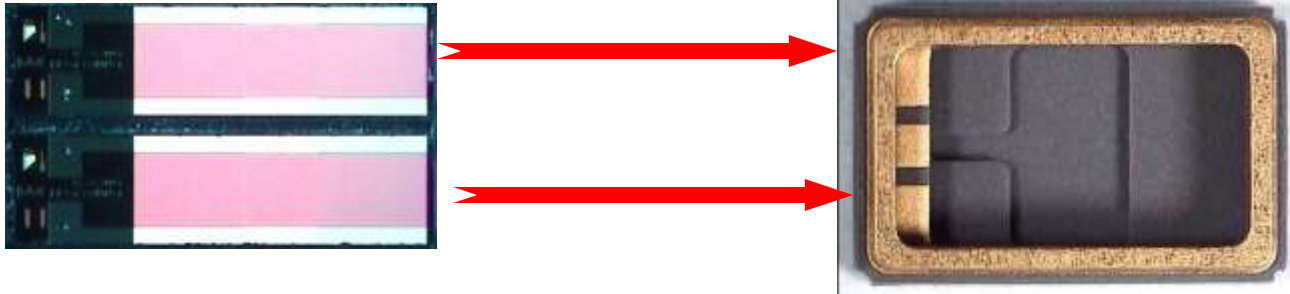


Temperature measurement system with 6 / 12 / 36 sensors

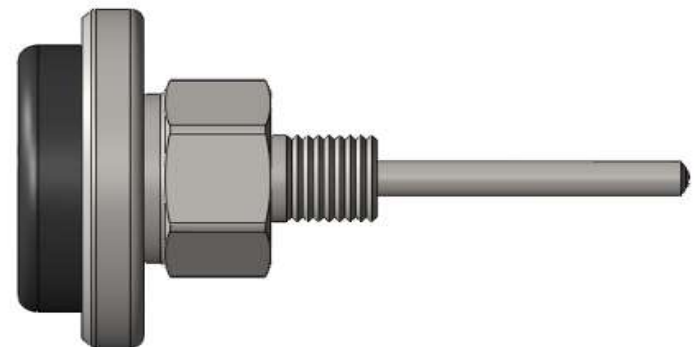
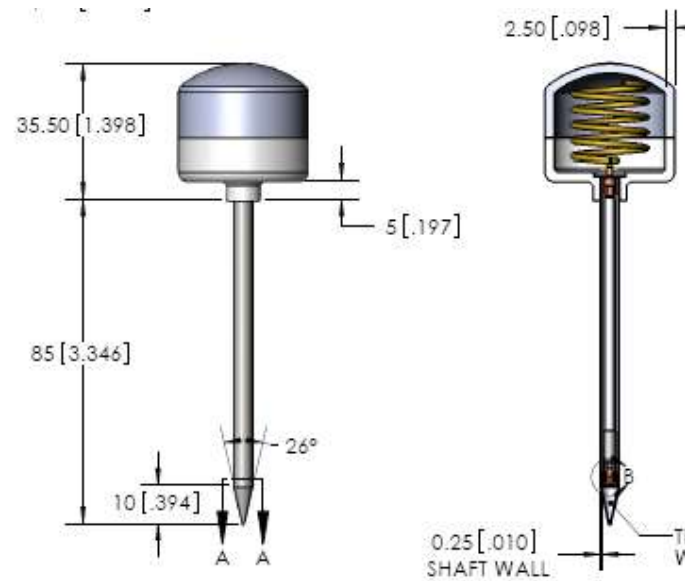


Types of sensor modules





Types of sensor modules



Absolute Measurement

- Measurement of absolute frequency of one resonator
- **Advantages:**
 - Less consumption of bandwidth
 - Easier frequency trimming of sensors in manufacturing
 - Faster interrogation
 - Slightly higher reading range
- **Disadvantages:**
 - Higher pulling effects
 - Higher ageing of frequency
 - More expensive frequency source for interrogation unit

Differential Measurement

- Measurement of absolute frequency of two resonances
- Difference frequency calculated from measured resonances
- **Advantages:**
 - Higher stability caused by lower pulling effects during sensor module manufacturing and caused by environment
 - Reduced ageing of difference frequency
 - Slightly cheaper reader architecture
- **Disadvantages:**
 - Higher bandwidth consumption
 - Questionable frequency trimming of difference frequency
 - Slightly slower interrogation
 - Slightly lower reading range

Specification:

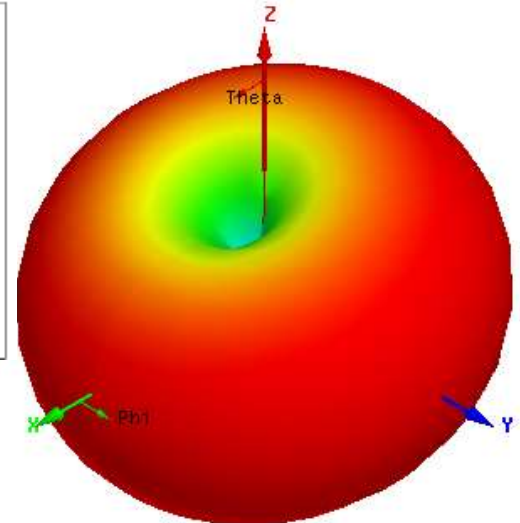
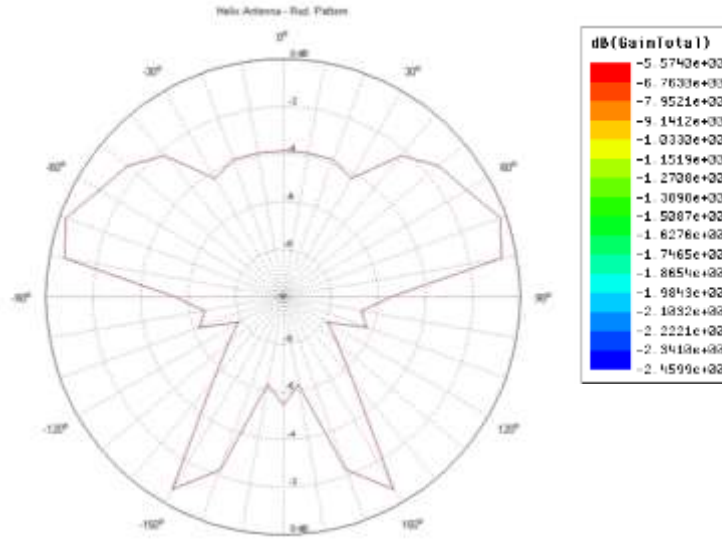
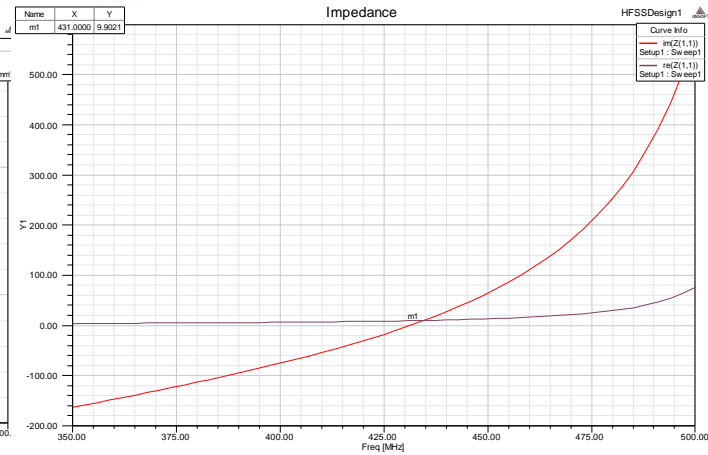
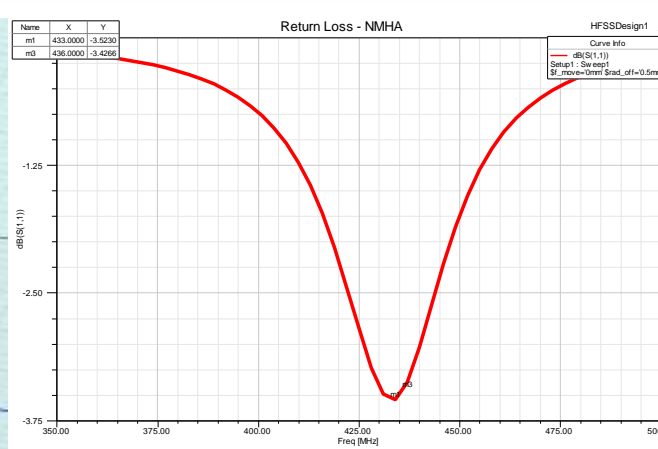
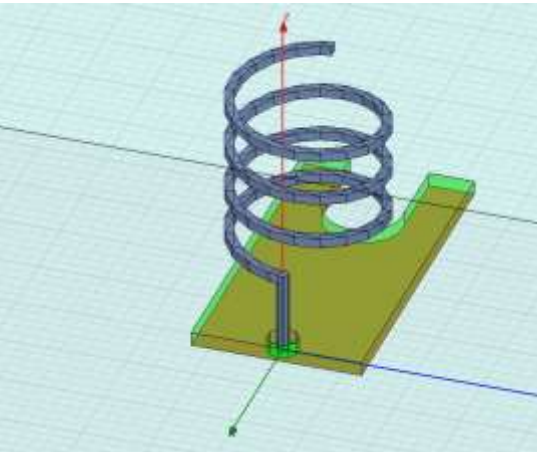
- Maximum possible temperature resolution Storage
- Maximum Echo or receive signal (Rx) level

Friis Formula:

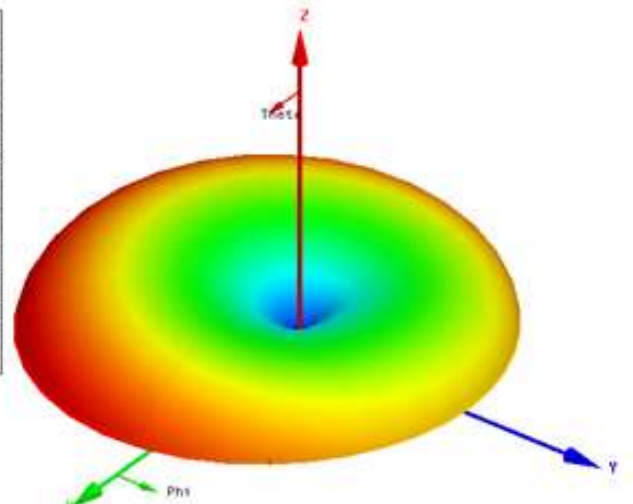
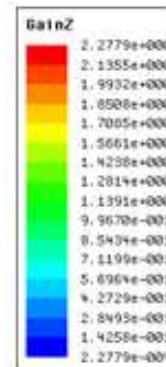
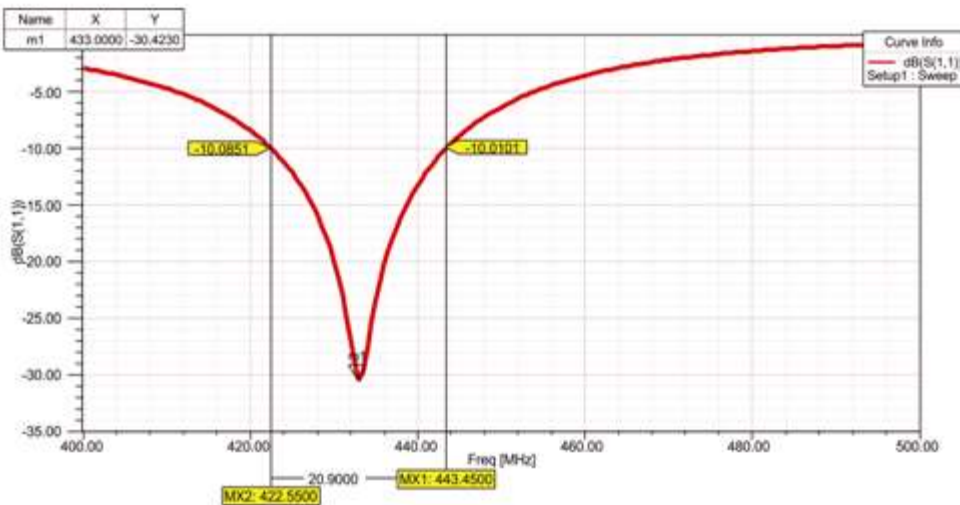
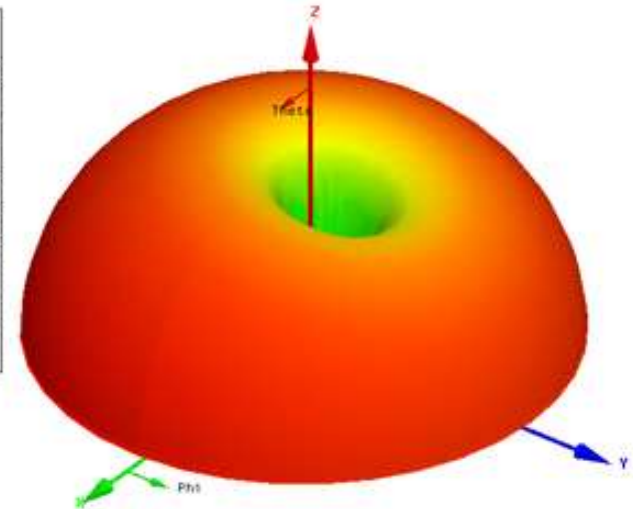
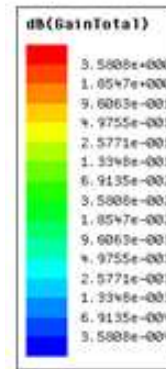
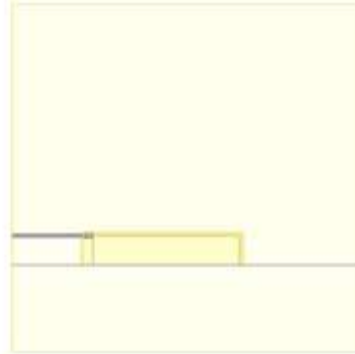
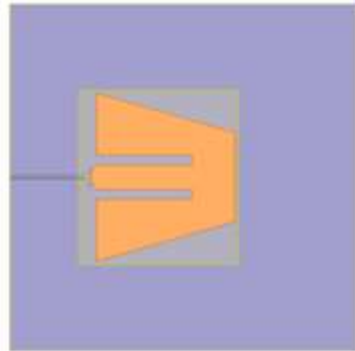
$$P_r = P_e \cdot \frac{G_i^2 \cdot G_{SAW}^2 \cdot \lambda^4}{(4 \cdot \pi \cdot r)^4} \cdot \alpha \cdot \underbrace{\left(1 - e^{\frac{-T}{\tau}}\right) \cdot \left(e^{\frac{t_{com}}{\tau}}\right)}_{Q - factor}$$

P_r : Receive power
 P_e : Reader output power
 G_i : Reader antenna gain
 G_{saw} : SAW sensor antenna gain
 r : Distance between Interrogator and sensor antennas
 α : matching/loss between antenna an sensor
 T/t_{co} : The interval of the transmission / commutation between Tx and RX

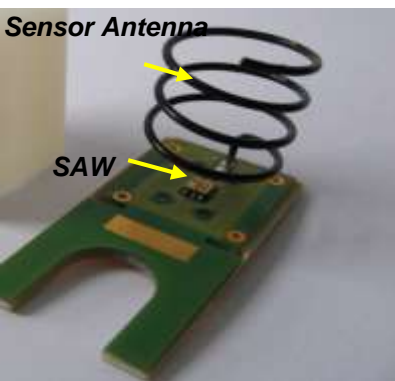
Sensor Antenna



Reader Antenna



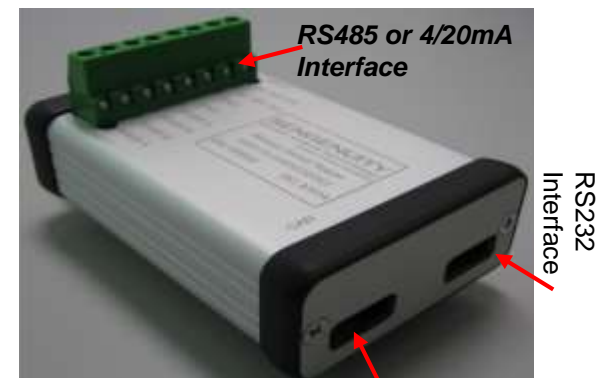
SAW Sensor Modules



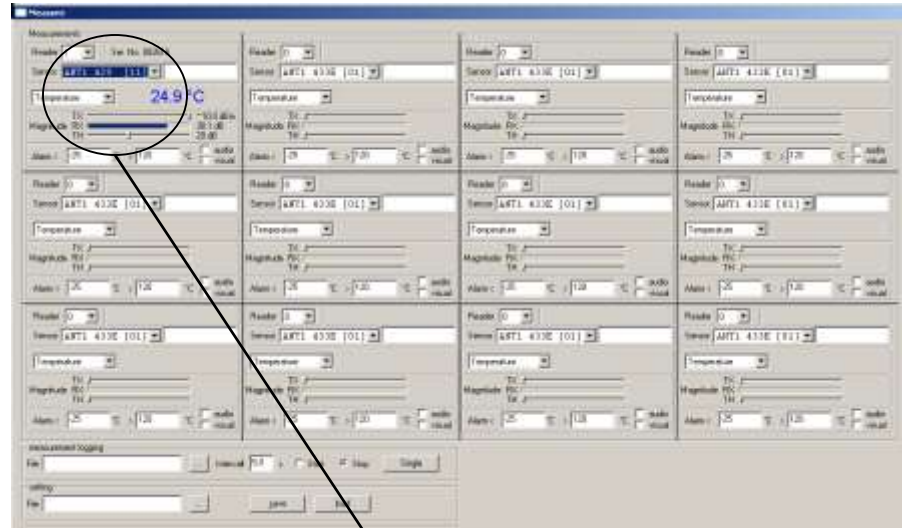
Reader Antennas



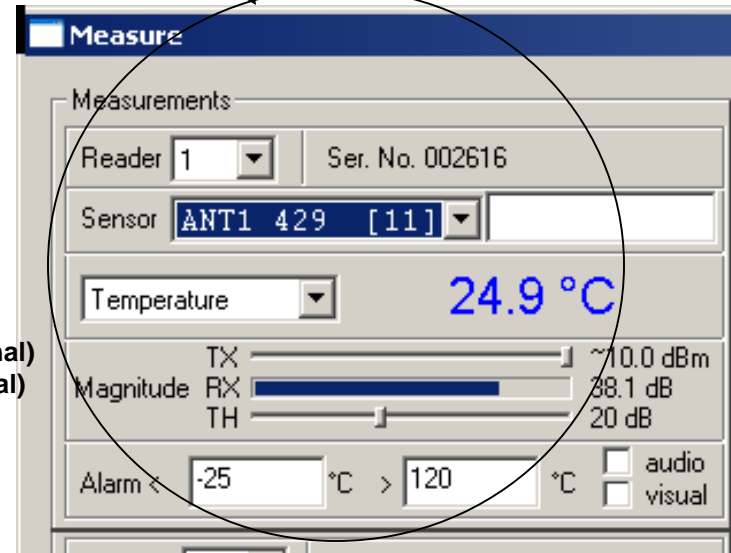
Reader Units



CAN Interface



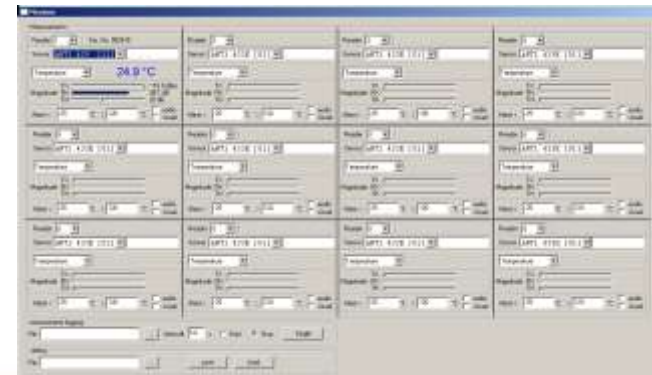
TX (Transmit signal)
RX (Receive signal)
TH (Threshold)



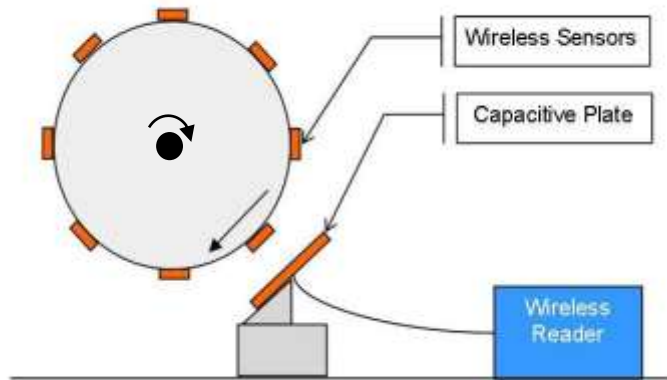
Temperature

Starter Kit: Wireless SAW Temperature Sensors

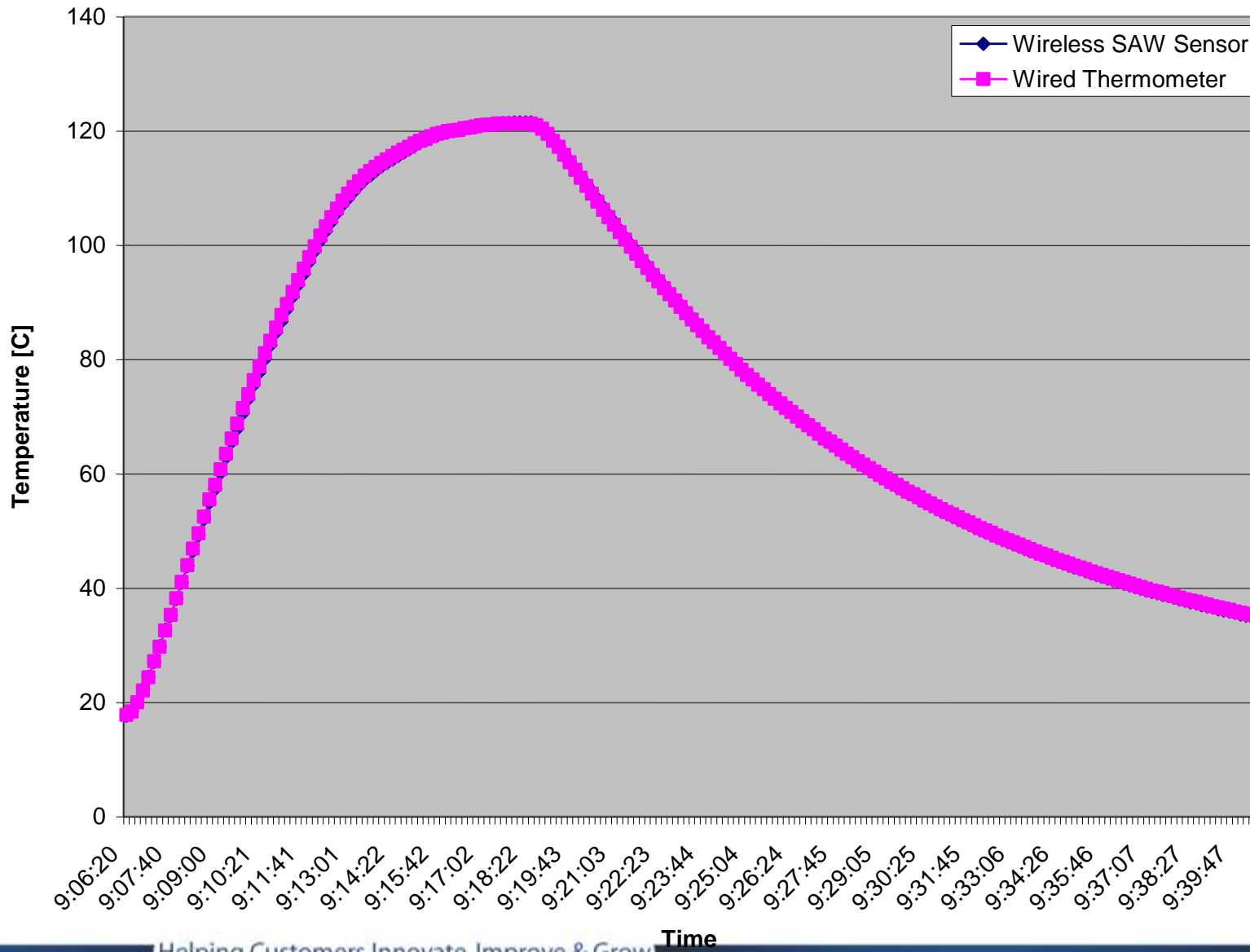
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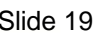
Applications

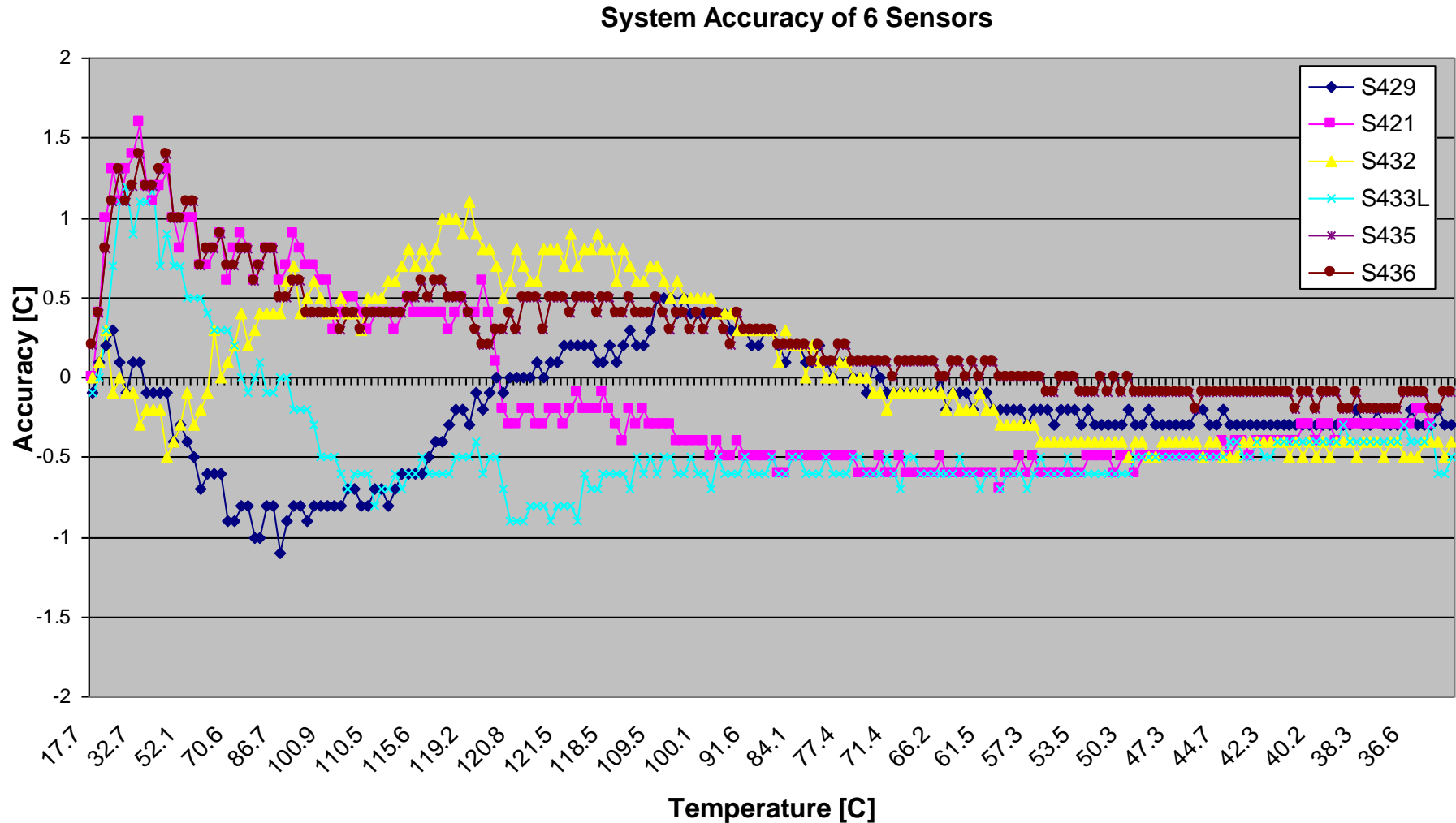


Wireless SAW & Thermometer



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Solution (Advantages)

- **Passive and Wireless**, non-invasive and no active electronic circuits
 - It has been estimated that typical wiring cost in industrial installation is US\$ 130 – 650 per meter and adopting wireless technology would eliminate 20% - 80% of this cost
- **Medium & High** temperature operating ranges: -20°C to 120°C & up to +260°C
- **Reading Distance**: 0.1 to 3 Meters (depend on the antenna and RF environment)
- **System accuracy**: $\pm 2^{\circ}\text{C}$ (temperature operating range -20°C to 120°C)
- **Robust, reliable, stable and suitable for harsh**, hazard and inaccessible hot-spots
- **Multi- Communication Protocol**: RS485, RS232, USB, CAN. Analog-Output, MODBUS
- **User Friendly**, ease of installation, simple to use Interfaces and data logging
- **Real-Time** and Continuously Thermal Monitoring – 24/7/365
- **Miniature**: small and light, low cost
- **Low Maintenances**
- **Low ageing degradations** ($\pm 2^{\circ}\text{C}$ <12 years)
- **Environmental** and green technology – no recycling of battery

Limitations

- **FCC/EC/EMC**
- **Number of Sensors - Interference**



Questions?

Thank You

www.sengenuity.com