Reliability and Performance Challenges of Next-Generation Smart Power Battery Management Systems for Electric Mobility

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- Introduction to BMS
- The vertical interface
- DPI and BCI simulations
- Investigation of failure mechanisms
- Conclusion



Lithium-ion (Li-ion) and Lithium-Polymer (LiPo) electrochemical battery packs

- ✓ High energy density
- ✓ High power capabilities

The presence of a
 Battery Management System (BMS)
 is essential

Under the risk of life-threatening hazards Due to:

Electromagnetic Interface (EMI)

The most critical EMI susceptibility issues are related to the vertical interface (VIF).















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VIF working principle:

Two different VIF structures are proposed

The BMS VIF transceivers are comprised of:

- ✓ Transmitter
- ✓ ESD protection circuit
- ✓ digital block
- ✓ Capacitive coupling network
- ✓ receiver
 - ✓ comparators
 - ✓ transmission resistor
 - ✓ common-mode voltage generator
- Main differences between the two structures:
 - ✓ Different CM input ranges for Comparators
 - Different threshold voltages for Comparators
 - ✓ Different overvoltage-overcurrent protections
 - ✓ Different electrostatic discharge (ESD) structures



VIF working principle:



A differential, capacitively isolated, bi-directional communication at 4 Mbit/s

A proprietary protocol is adopted

- Logic "1": a positive differential pulse followed by a negative one
- Logic "0": a negative differential pulse followed by a positive one
- An idle time between each transmitted bit







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Evaluation of the susceptibility to EMI





Susceptibility level to EMI





- ✓ A clear correlation between the DPI and BCI simulation results
- ✓ More susceptible to low-frequency EMI
- ✓ For VIF#1 the DPI (BCI) failure level is as low as 0 dBm (73.5 dBmA)
- ✓ For VIF#2 the DPI (BCI) failure level reaches 27.5 dBm (101.9 dBmA)







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Benchmark Parameters



Dint: The mean value of the comparator input differential signal exceeding the threshold voltages

$$\Delta Int = \frac{\int_{TF}^{TL} |v_{in} - V_{th}| dt}{|TL - TF|}$$

DSig: The distance between VthP (VthM) and the maximum (minimum) of the signal during a low (high) pulse

Didl: The minimum distance between the signal and the thresholds (VthM, and VthP) during the idle time

✓ the closer the parameters are to zero, the closer the transmission is to a failure condition







Phase Shifting Effect on DPI Simulation Results



Two examples of different RF signal initial phases: 5MHz, 40MHz

Based on results:

• Variation in initial phase leads to the variation in the differential signal of the comparator's inputs

Benchmark parameters for the first bit after power injection for the VIF#2

Based on results:

- Strong dependency of parameters in lower frequency on the initial phase
- No longer dependency for frequencies above 30 MHz
- In almost all cases the Dsig equals to $2V_{th}$







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Conclusion



Imbalances in the structure and/or rectification phenomena in the ESD protections

Conversion of common mode into differential mode interference

Differential mode component of the received signal at the input of the comparators is corrupted by EMI

Whenever the parameters are passed, comparators operate in a way that the output digital bit is correctly generated

Future research are being done focusing on the mechanisms leading to CM to DM conversion





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Thank you for your attention



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