

Levy Differential Evolutionary Particle Swarm Optimization (LEVY DEEPSO)

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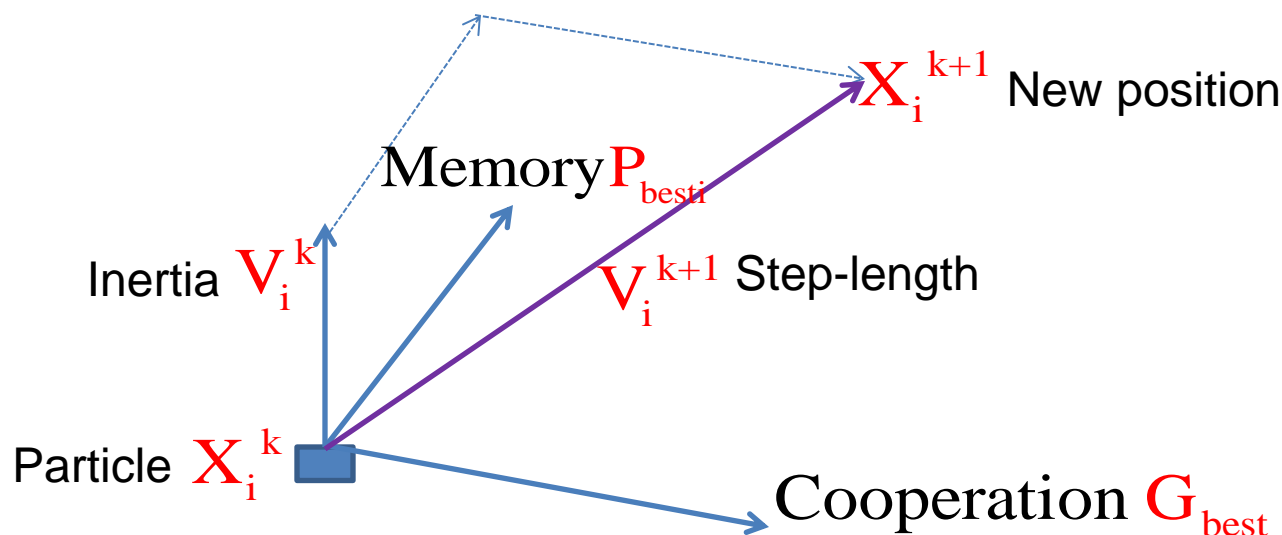
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Particle Swarm Optimization[1]

- Particles: Possible solutions in the feasible space
- Velocity (Step-length) of a particle i:

$$V_i^{k+1} = w_I \cdot V_i^k + R_1 \cdot w_M \cdot (P_{besti} - X_i^k) + R_2 \cdot w_C \cdot (G_{best} - X_i^k)$$



Particle Swarm Optimization

- Velocity of a particle is influenced by:

(1) Inertia

Follow in the same direction

(2) Personal memory

Follow particle's personal best obtained so far

(3) Cooperation

Follow the global best particle

Particle Swarm Optimization

- New position of a particle i :

$$\mathbf{X}_i^{k+1} = \mathbf{X}_i^k + \mathbf{V}_i^{k+1}$$

Differential Evolutionary PSO (DEEPSO)[2]

- Velocity updating rule:

$$V_i^{k+1} = w_I^* \cdot V_i^k + w_M^* \cdot (X_{r1} - X_i^k) + w_C^* \cdot P \cdot (G_{best}^* - X_i^k)$$

(1) Inertia

Follow the same direction

(2) Perception

Follow the randomly sampled particle chosen from the matrix of individual past bests

(3) Cooperation

Follow the mutated global best particle

DEEPSO

- Each weight and global best particle are subject to mutation as follows

$$W^* = W(1 + \tau \cdot N[0,1])$$

- P = communication probability
- Allow communication $\Leftrightarrow \text{rand}() < P$

Research challenge

- Optimization involves....
- **Global Exploration: To explore unknown and large-scale search space**
- Local Exploitation

Levy flight (Step)[3]

- Levy flight: It is a random walk whose step length is drawn from the Levy distribution.
- Levy distribution is defined as follows:

- $$L(s, \gamma, \mu) = \begin{cases} \sqrt{\frac{\gamma}{2\Pi}} \cdot \exp\left[-\frac{\gamma}{2(s-\mu)}\right] \cdot \frac{1}{(s-\mu)^{3/2}}, & 0 < \mu < s < \infty \\ 0 & \text{otherwise} \end{cases}$$

where,

$\mu > 0$ is a minimum step

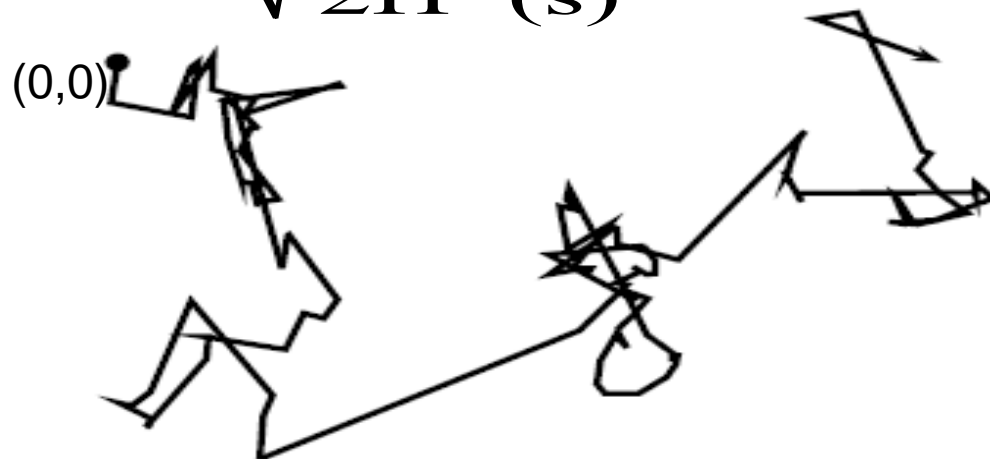
γ is a scale parameter

Levy flight (Step) cont..

- Generalized Levy distribution:

as $s \rightarrow \infty$,

$$L(s, \gamma, \mu) \approx \sqrt{\frac{\gamma}{2\Pi}} \cdot \frac{1}{(s)^{3/2}}$$



- Levy flights in 50 consecutive steps starting at origin(0,0)[3]

Levy Step cont....

- Many animals (e.g. Silky sharks and swordfish) and insects make use of Levy flights to search the food. [4]
- Light can be related to levy flight[5]

Mathematical formulations of Levy step [3]

$$\text{Step length} = \frac{u}{|v|^{1/\beta}}$$

where,

$$\beta = 3/2;$$

u and v are drawn from normal distributions as follows

$$u \sim \mathbf{N}(0, \sigma_u^2)$$

where,

$$\sigma_u = \left\{ \frac{\Gamma(1+\beta) * \sin(\Pi * \beta / 2)}{\Gamma[(1+\beta)/2] * \beta * 2^{(\beta-1)/2}} \right\}^{1/\beta}$$

$$\mathbf{v} \sim \mathbf{N}(\mathbf{0}, \sigma_v^2)$$

where

$$\sigma_v = 1$$

$$\text{Levystep} = \alpha * \text{step length} * (X_i^k - G_{\text{best}})$$

where,

$\alpha = \text{Levy_constant}$

$\alpha = (\text{mean}(X_{\text{max}} - X_{\text{min}})) / 100;$

Levy Differential Evolutionary Particle Swarm Optimization (LEVY DEEPSO)

- Proposed Velocity updating rule:

$$V_i^{k+1} = w_I^* \cdot V_i^k + w_M^* \cdot (X_{r1} - X_i^k) + w_C^* \cdot P \cdot (G_{best}^* - X_i^k) + \alpha \cdot \frac{u}{|v|^{1/\beta}} \cdot (X_i^k - G_{best})$$

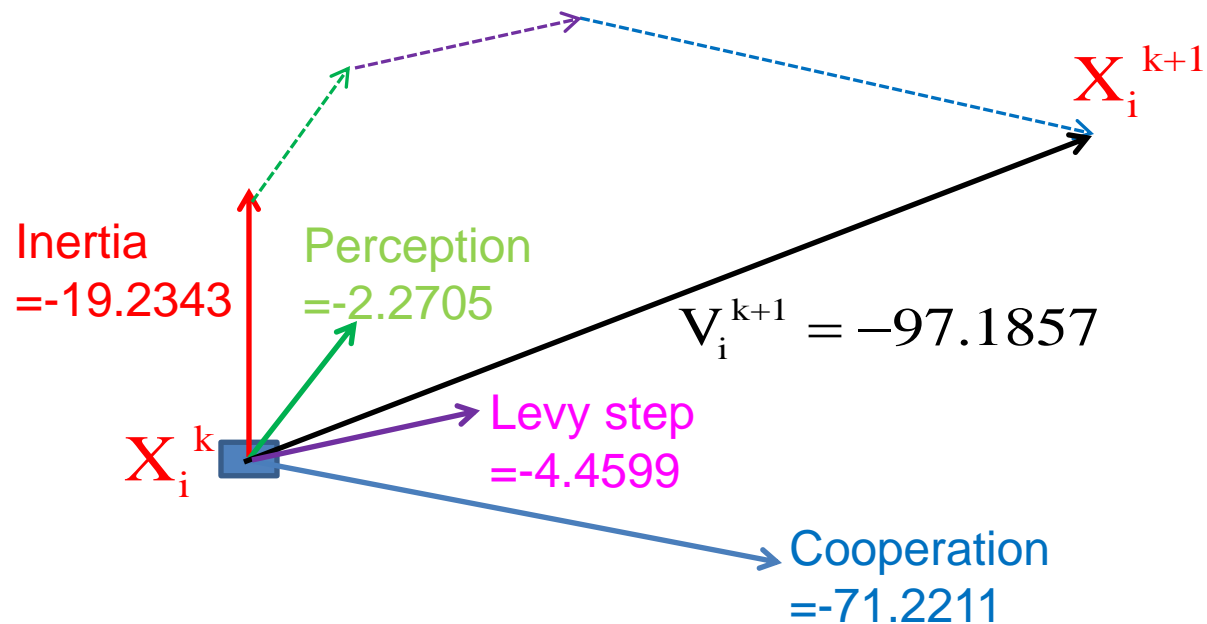
(1) Inertia

(2) Perception

(3) Cooperation

(4) Levy step

Velocity components of WT-2 active output power (Case-1)



Levy DEEPSO parameters

Parameters	Symbol	Numerical value
Populations size	N	100
Levy Exponent	β	1.5 (Levy distribution)
		1 (Cauchy distribution)
		2 (Normal distribution)
Levy Coefficient	σ_u	0.6966
Mutation Rate	τ	0.5
Communication Probability	P	0.5

OPF Constraints

- Equality constraints: Power balance equations
- Inequality constraints:
 - Max. active power output of slack generator
 - Nodal voltages and load angles for load buses
 - Generator reactive power capability
 - Allowable branch power flows

Constraint Handling Method

- Select the maximum of the average sum of deviations at iteration T [6]

$$\max \left(\frac{1}{T-1} \sum_{t=1}^{T-1} \sum |\Delta P_{t-1}|, \frac{1}{T-1} \sum_{t=1}^{T-1} \sum |\Delta V_{t-1}|, \frac{1}{T-1} \sum_{t=1}^{T-1} \sum |\Delta Q_{t-1}|, \frac{1}{T-1} \sum_{t=1}^{T-1} \sum |\Delta S_{t-1}| \right)$$

Simulation Results: Test bed 1

- MATLAB 2014a, Intel core i7-2600 CPU with 8.00 GB RAM
- Cases:1 & 4:- IEEE 57-bus system with 3 wind generators.

Stats.	Case:1	Case:4
fbest	72683.2050000	72899.2898699
o@fbest	72683.2030000	72899.2878940
g@fbest	0.0020000	0.0019759
fworst	72711.0200000	72946.6329200
fmean	72693.4419032	72910.9009446
fmedian	72691.7280000	72908.5313215
fstd	7.8654229	11.0157609

Simulation Results cont....

- Cases:2 & 5:- IEEE 57-bus system with 2 wind generators and 01 solar generator.

Stats.	Case:2	Case:5
fbest	72046.6066509	71689.7826879
o@fbest	72046.6001290	71689.7807285
g@fbest	0.0065219	0.0019594
fworst	72087.6270438	71731.3254569
fmean	72064.9103084	71700.9445623
fmedian	72066.6457403	71696.0686322
fstd	10.7606750	10.55165807

Simulation Results cont....

- Cases:3 & 6:- IEEE 57-bus system with 01 wind generator and 02 solar and small-hydro generators.

Stats.	Case:3	Case:6
fbest	60285.5868115	61278.5378234
o@fbest	60285.5842623	61278.5359725
g@fbest	0.0025492	0.0018509
fworst	60333.8249495	61326.3446038
fmean	60299.3470939	61292.5909826
fmedian	60297.0594339	61289.4746795
fstd	12.106446	10.7437215

References

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