



Physics-Informed Neural Networks and Verification for Power Systems

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This work would not have been possible without the hard work of several people! Many thanks to...



Andreas Venzke



Rahul Nellikkath



Ilgiz Murzakanov



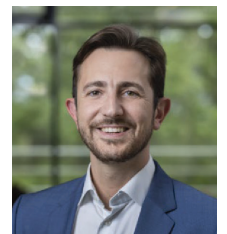
Lejla Halilbasic



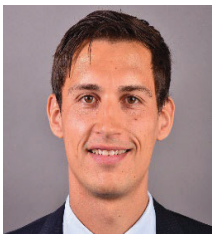
Elea Prat



Jochen Stiasny



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Florian Thams



Georgios Misyris



Sam Chevalier



Brynjar Sævarsson

And to our collaborators:

Dan Molzahn, GeorgiaTech

Steven Low, Caltech

Guannan Qu, Caltech (now at CMU)

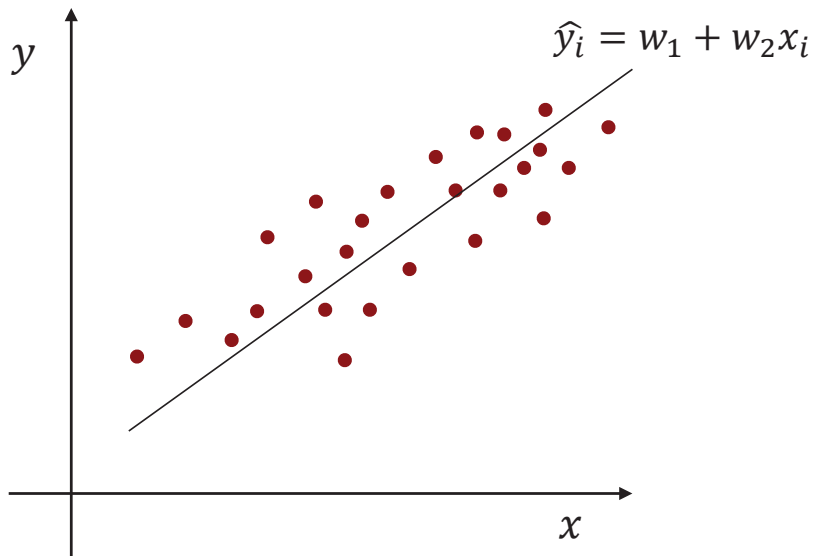
Machine Learning in Power Systems: Why?

- Machine learning “surrogate” models can deliver solutions **100-1’000 faster** than conventional models with acceptable accuracy
- ML models can be used to **screen very fast a very large number of scenarios**, in order to focus on the critical ones
- **Problem #1: Data is not enough**
 - Available data might be scarce or might not cover all abnormal situations.
 - Potential solution: Learn from the physics → **Physics-Informed Machine Learning**
- **Problem #2: Can we trust the outputs of the ML models?**
 - Potential solution: **Trustworthy ML**

Transient Stability Assessment with Physics-Informed Neural Networks

DTU Neural Networks: An advanced form of non-linear regression

y_i : actual/correct value
 \hat{y}_i : estimated value



Loss function: Estimate best w_1, w_2 to fit the training data

$$\begin{aligned} & \min_{w_1, w_2} \|y_i - \hat{y}_i\| \\ \text{s.t.} & \hat{y}_i = w_1 + w_2 x_i \quad \forall i \end{aligned}$$

Traditional training of neural networks required no information about the underlying physical model. Just data!

“Original”
Loss function

“Physics-Informed”
term

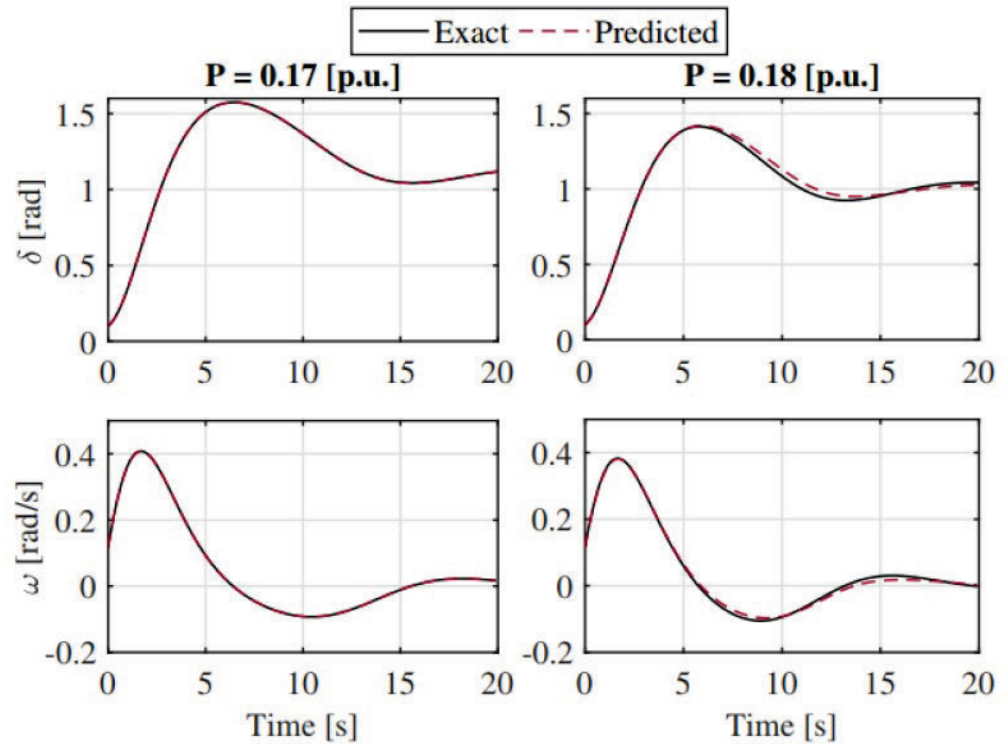
$$\min_{\mathbf{W}, \mathbf{b}} \frac{1}{|N_\delta|} \sum_{i \in N_\delta} |\hat{\delta} - \delta^i|^2 + \frac{1}{|N_f|} \sum_{i \in N_f} |f(\hat{\delta})|^2 \quad (6a)$$

$$s.t. \quad \hat{\delta} = NN(t, P_m, \mathbf{W}, \mathbf{b}) \quad (6b)$$

$$\dot{\hat{\delta}} = \frac{\partial \hat{\delta}}{\partial t}, \quad \ddot{\hat{\delta}} = \frac{\partial^2 \hat{\delta}}{\partial t^2} \quad (6c)$$

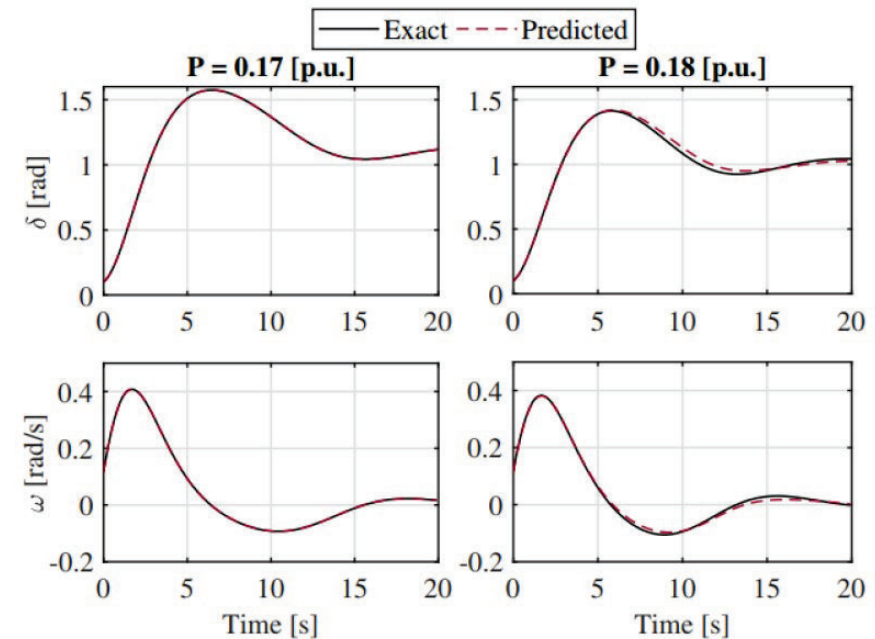
$$f(\hat{\delta}) = M\ddot{\hat{\delta}} + D\dot{\hat{\delta}} + A \sin \hat{\delta} - P_m \quad (6d)$$

Swing equation



G. S. Misyris, A. Venzke, S. Chatzivasileiadis, Physics-Informed Neural Networks for Power Systems. Presented at the Best Paper Session of IEEE PES GM 2020. <https://arxiv.org/pdf/1911.03737.pdf>

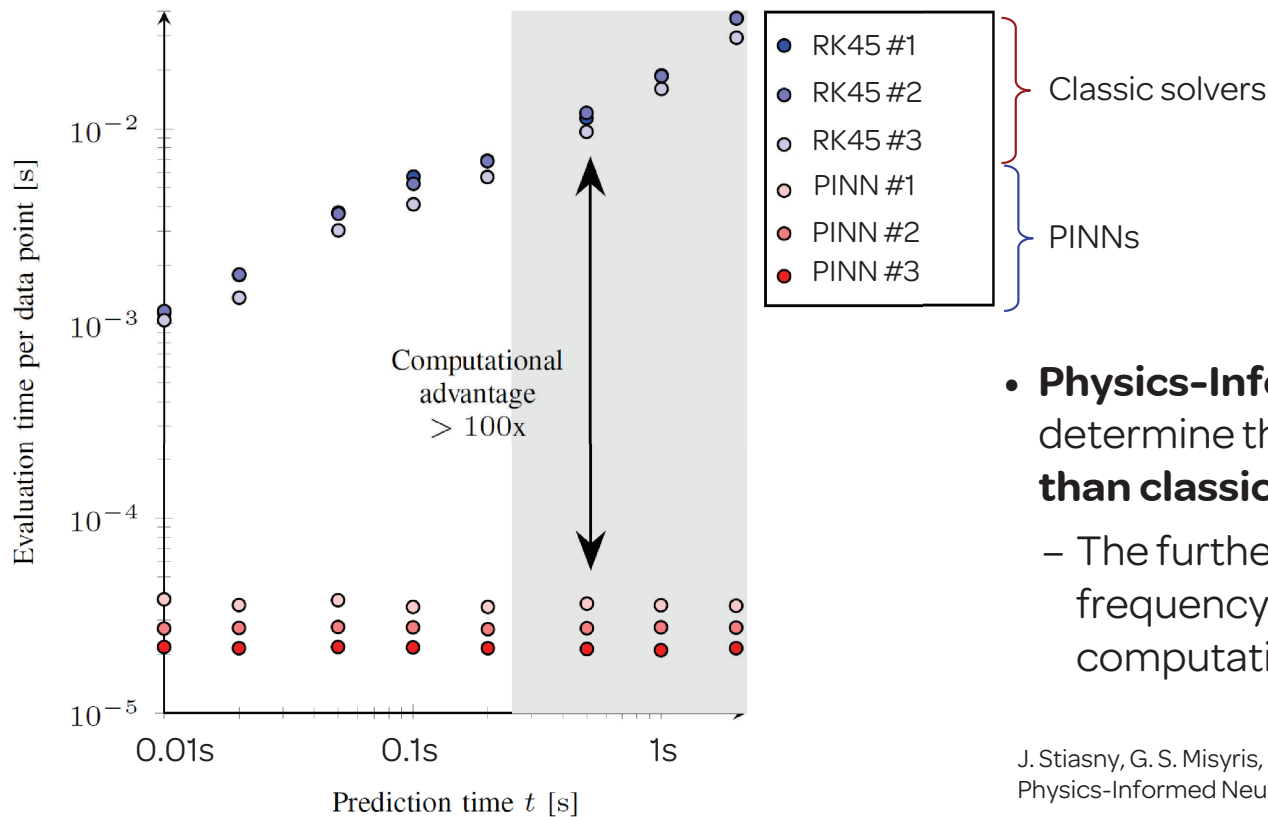
- Physics-Informed Neural Networks (PINN) could potentially replace solvers for systems of differential-algebraic equations in the long-term
 - **Probable power system application: Extremely fast screening of critical contingencies**
- In our example: PINN 87 times faster than ODE solver
- Can **directly estimate** the rotor angle at **any** time instant



Code is available on GitHub: <https://github.com/jbesty>

G. S. Misyris, A. Venzke, S. Chatzivasileiadis, Physics-Informed Neural Networks for Power Systems. Presented at the Best Paper Session of IEEE PES GM 2020. <https://arxiv.org/pdf/1911.03737.pdf>

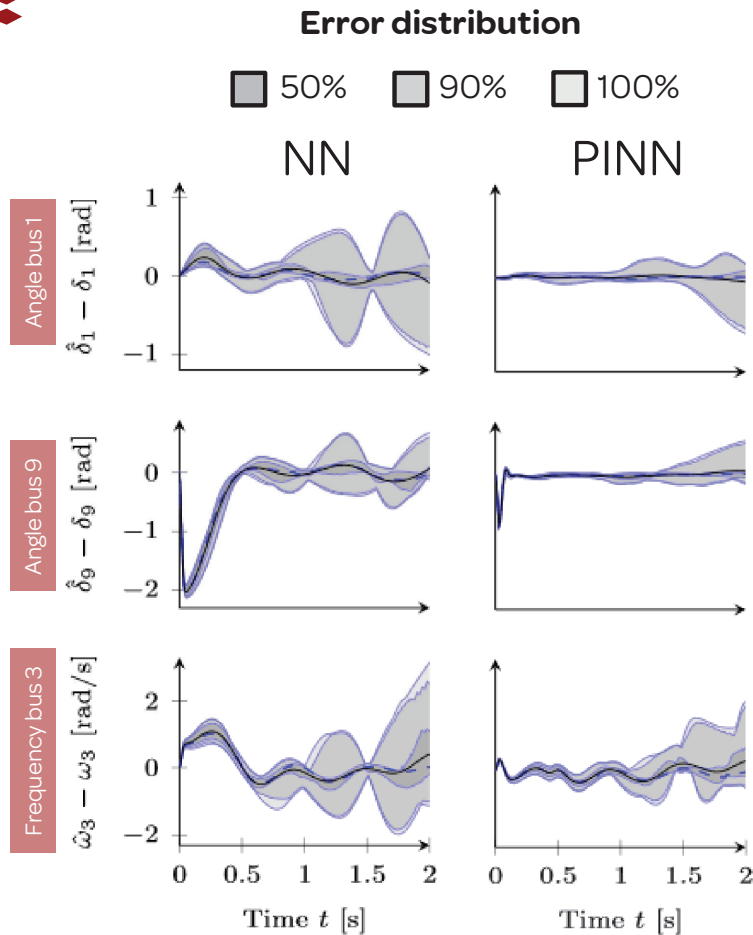
Computation time: Classical numerical solvers vs. Physics-Informed NNs



- **Physics-Informed Neural Networks** can determine the outputs more than **100x faster than classical numerical solvers**
 - The further we look in time, e.g. what is the frequency at $t=1s$, the larger the computational advantage is

J. Stiasny, G. S. Misyris, S. Chatzivasileiadis, Transient Stability Analysis with Physics-Informed Neural Networks. <https://arxiv.org/abs/2106.13638> [code]

Accuracy: Standard Neural Networks (NN) vs Physics-Informed NNs (PINN)



- **PINNs result in lower errors** than standard neural networks
- The error increases as we look further into the future
- PINNs can deliver an excellent screening tool, i.e. to very quickly assess if critical scenarios are secure or not.
 - To determine the exact numerical values, classic solvers are still very valuable

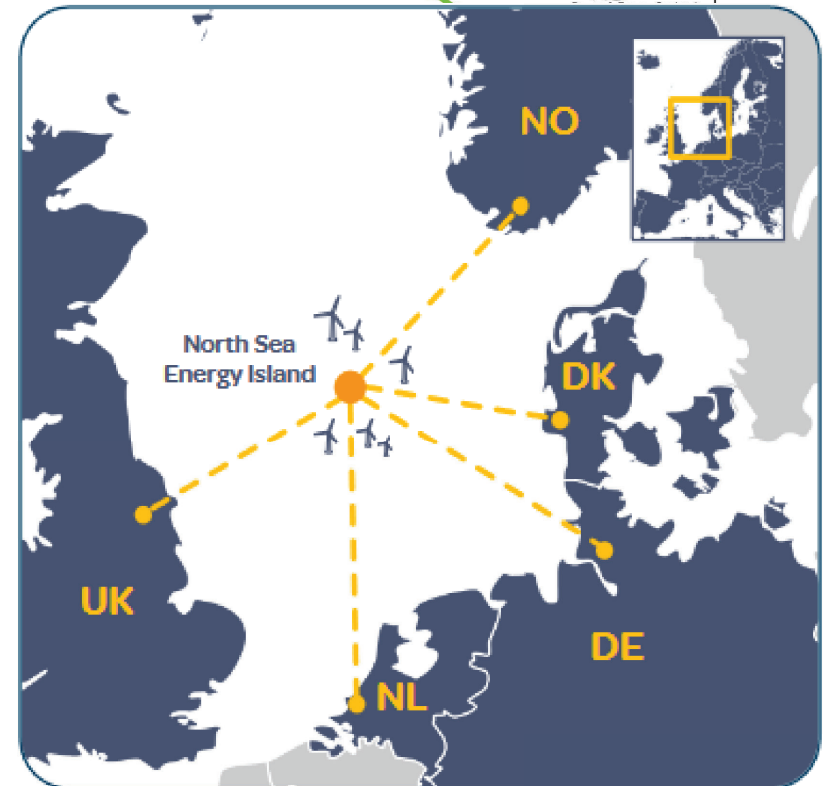
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Small-signal stability assessment and tuning of controller gains with trustworthy neural networks

An Example

- North Sea Wind Power Hub
- Wind Hub Operators offer **energy and primary frequency control and primary voltage control**
 - Can determine both P and Q, **and**
 - $K_{p,f}$ and K_v (freq. droop and voltage droop)
- What are the permissible combinations of P, Q, $K_{p,f}$, and K_v that satisfy:
 - Small-signal Stability (e.g. $\zeta > 3\%$), **for all**
 - N-1 contingencies

Problem extremely difficult to solve: infinite combinations

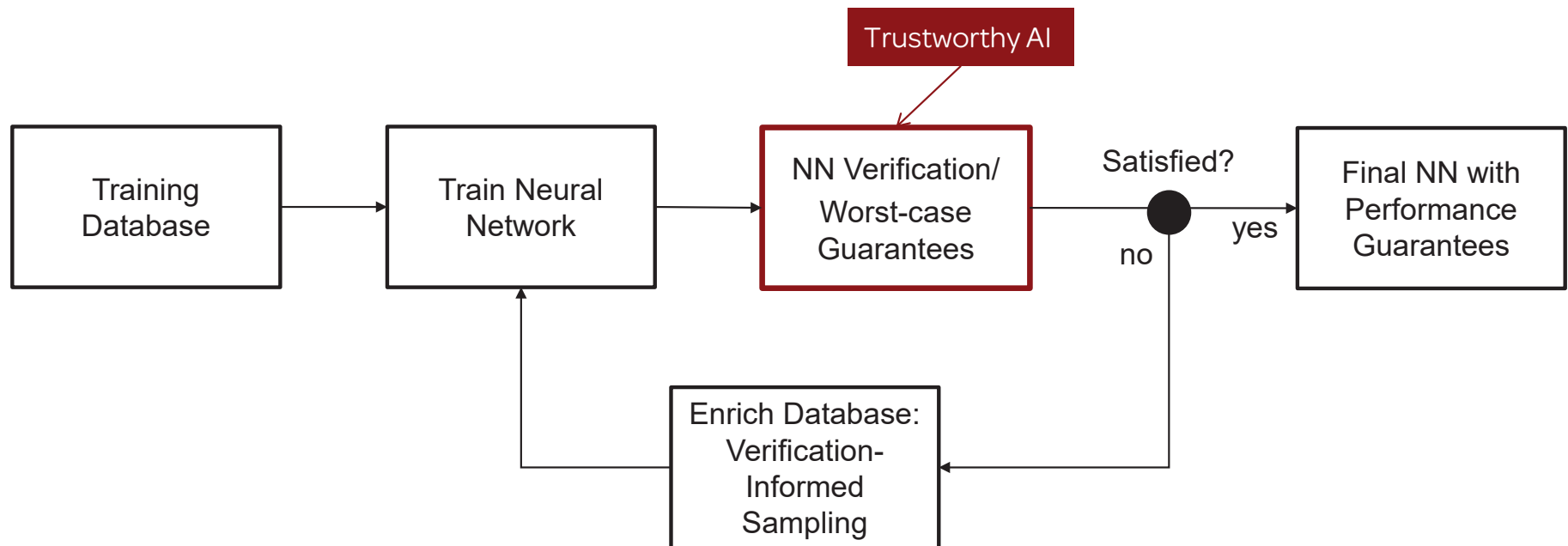


J. Stiasny, S. Chevalier, R. Nellikkath, B. Sævarsson, S. Chatzivasileiadis. Closing the Loop: A Framework for Trustworthy Machine Learning in Power Systems. Accepted to 2022 iREP Symposium - Bulk Power System Dynamics and Control - XI (iREP). Banff, Canada. 2022. [[paper](#) | [code](#)]

Step 1:

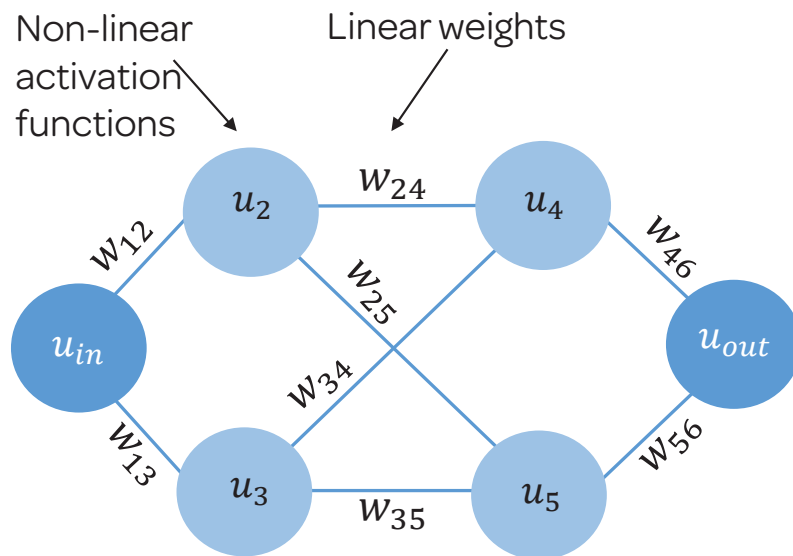
Learn the permissible region of $P, Q, K_{p,f}$, and K_v

Goal: satisfy small-signal stability margin for all N-1 contingencies

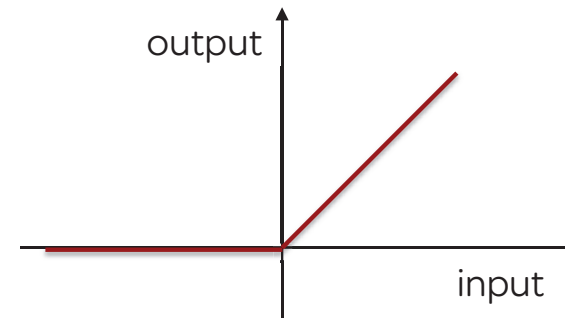


1. **Exact transformation:** Convert the neural network to a **set of linear equations with binaries**
 - The Neural Network can be included in a mixed-integer linear program
2. Formulate an **optimization** problem (MILP) and solve it → certificate for NN behavior
3. Assess if the neural network output complies with the ground truth

From Neural Networks to Mixed-Integer Linear Programming

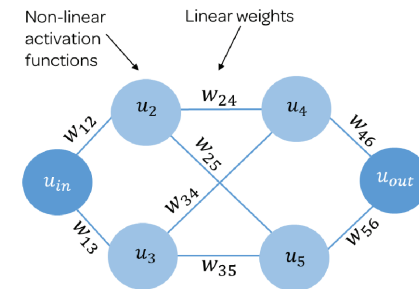
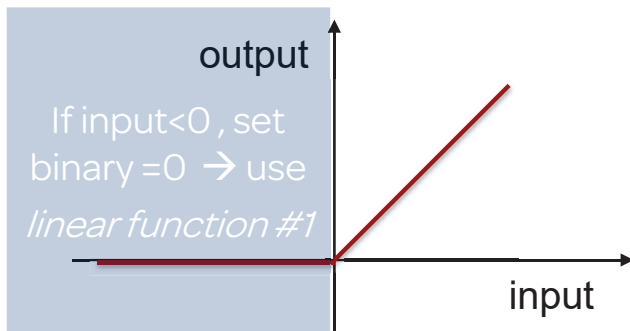


- Most usual activation function: ReLU
- **ReLU**: Rectifier Linear Unit



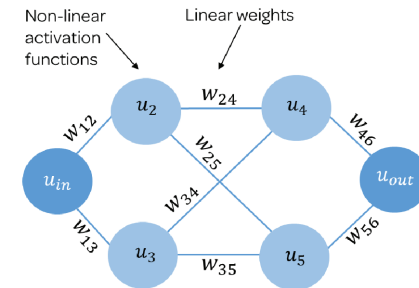
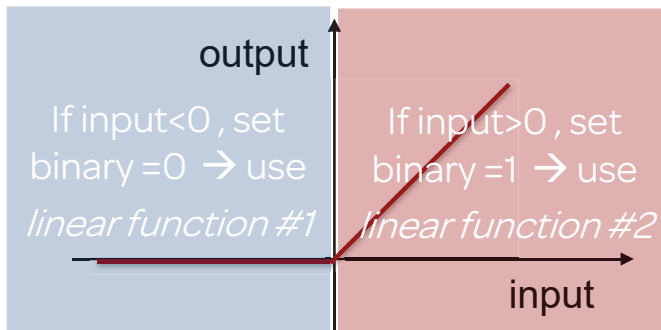
From Neural Networks to Mixed-Integer Linear Programming

1. But **ReLU** can be transformed to a **piecewise linear function with binaries**



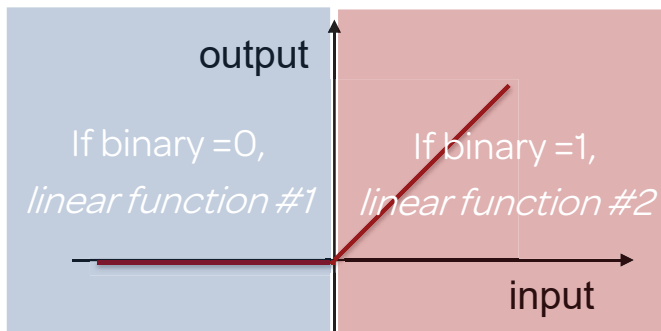
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From Neural Networks to Mixed-Integer Linear Programming

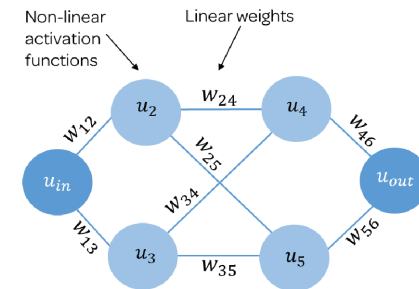
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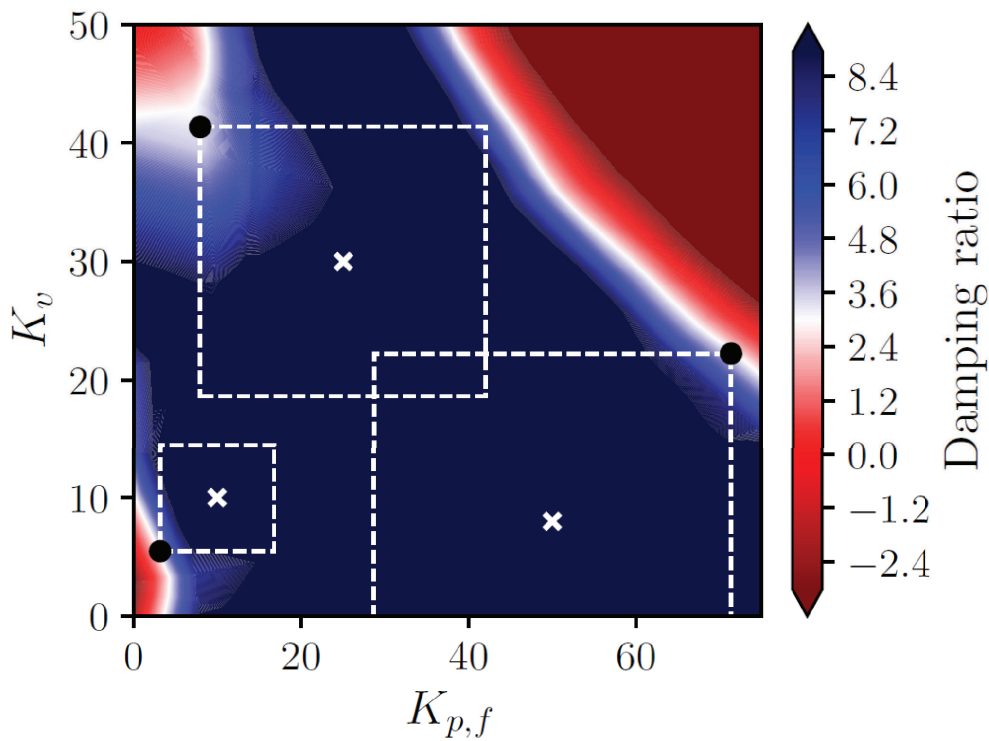
2. I can encode all operations of a Neural Network to a system of linear equations with continuous and binary variables



3. I can **integrate** all information encoded in a **neural network inside an optimization program**



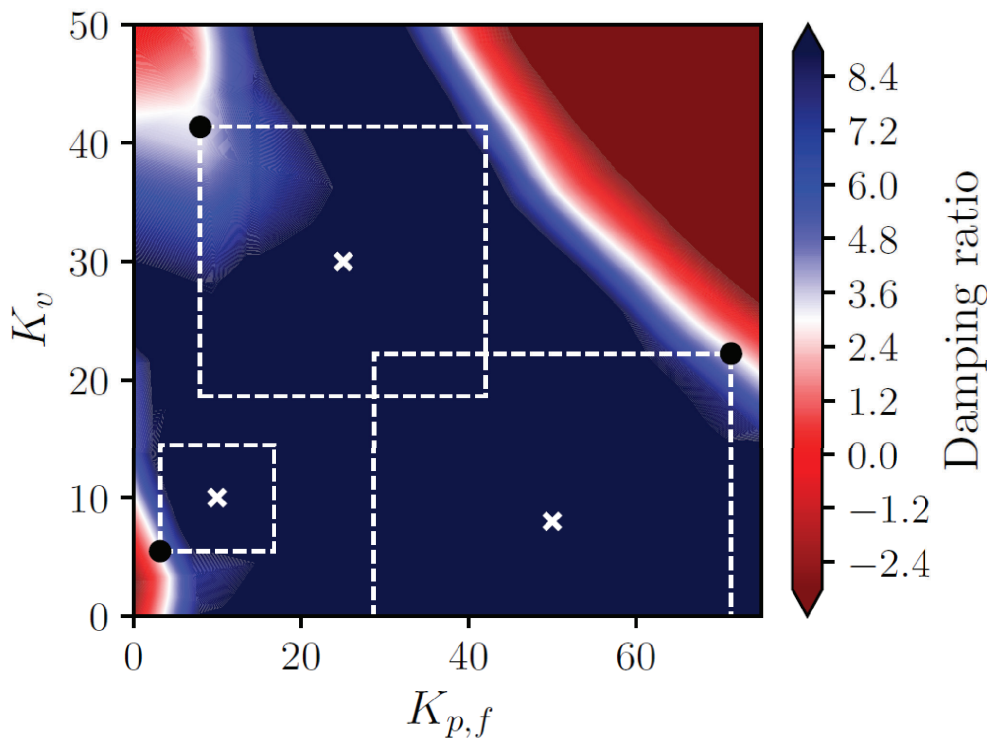
Certify the output for a continuous range of inputs



1. We assume a given input x_{ref} with classification "safe"

A. Venzke, S. Chatzivasileiadis. Verification of Neural Network Behaviour: Formal Guarantees for Power System Applications. *IEEE Transactions on Smart Grid*, Jan. 2021. <https://arxiv.org/pdf/1910.01624.pdf>

Certify the output for a continuous range of inputs



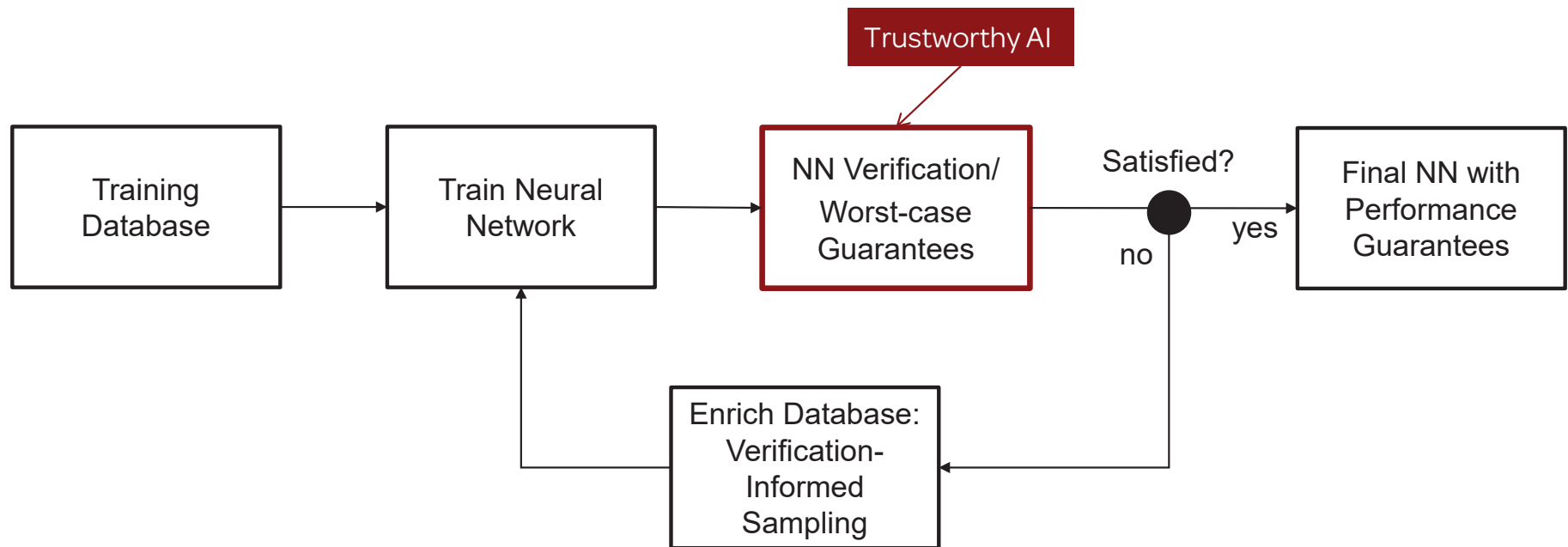
1. We assume a given input x_{ref} with classification "safe"
2. Solve optimization problem: **Find the minimum distance for which the classification changes?**
3. **Outcome:**
 - a) **I can certify** that my neural network will classify the whole continuous region as "safe"
 - b) I have either identified the classification **boundary or a misclassified point** \rightarrow sample around it and **enrich** the training database

A. Venzke, S. Chatzivasileiadis. Verification of Neural Network Behaviour: Formal Guarantees for Power System Applications. *IEEE Transactions on Smart Grid*, Jan. 2021. <https://arxiv.org/pdf/1910.01624.pdf>

Step 1:

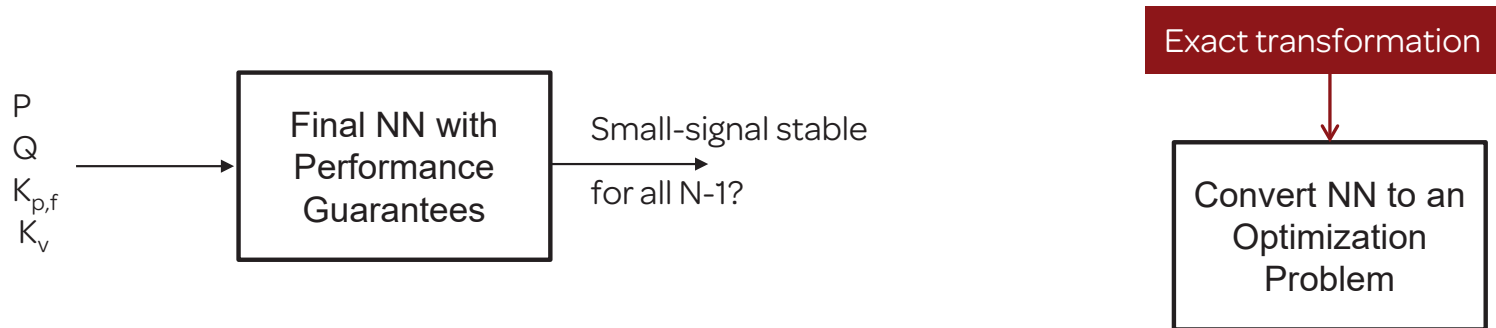
Learn the permissible region of $P, Q, K_{p,f}$, and K_v

Goal: satisfy small-signal stability margin for all N-1 contingencies



Step 2: Convert Verified Neural Network to an Optimization Problem

Goal: satisfy small-signal stability margin for all N-1 contingencies



Optimization Problem #1

For given P_{ref}^* , Q_{ref}^* , what is the maximum range of $K_{p,f}$ and K_v around $K_{p,f,0}$ and $K_{v,0}$ that ensures small-signal stability for all N-1 contingencies?

Optimization Problem #2

For given $K_{p,f}^*$ and K_v^* , what is the maximum range of P_{ref} and Q_{ref} around $P_{ref,0}$ and $Q_{ref,0}$ that ensures small-signal stability for all N-1 contingencies?

- Physics-Informed Neural Networks use the underlying physical models to estimate solutions 100-1'000 faster than conventional models
 - useful for screening very fast large number of scenarios

- Trustworthy AI can help determine permissible ranges of operation that
 - would be very difficult to determine otherwise
 - with a predefined level of trust (worst-case guarantees)



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- J. Stiasny, G. S. Misyris, S. Chatzivasileiadis, Transient Stability Analysis with Physics-Informed Neural Networks. <https://arxiv.org/abs/2106.13638> [code]
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- I. Murzakhonov, A. Venzke, G. S. Misyris, S. Chatzivasileiadis. Neural Networks for Encoding Dynamic Security-Constrained Optimal Power Flow to Mixed-Integer Linear Programs. Accepted to *2022 iREP Symposium - Bulk Power System Dynamics and Control - XI (iREP)*. Banff, Canada. 2022. [paper]
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- A. Venzke, S. Chatzivasileiadis. Verification of Neural Network Behaviour: Formal Guarantees for Power System Applications. IEEE Trans. on Smartgrid. 2021. <https://arxiv.org/pdf/1910.01624.pdf>
- A. Venzke, G. Qu, S. Low, S. Chatzivasileiadis, Learning Optimal Power Flow: Worst-case Guarantees for Neural Networks. **Best Student Paper Award** at IEEE SmartGridComm 2020. [.pdf | slides | video]
- G. S. Misyris, A. Venzke, S. Chatzivasileiadis, Physics-Informed Neural Networks for Power Systems. Presented at the **Best Paper Session** of IEEE PES GM 2020. <https://arxiv.org/pdf/1911.03737.pdf>

Article without any equations ☺

S. Chatzivasileiadis, A. Venzke, J. Stiasny and G. Misyris, "**Machine Learning in Power Systems: Is It Time to Trust It?**," in *IEEE Power and Energy Magazine*, vol. 20, no. 3, pp. 32-41, May-June 2022 [.pdf]

All publications available at:

www.chatziva.com/publications.html

Some code available at:

www.chatziva.com/downloads.html