

# A view from inside a distributed Internet coordinate system.

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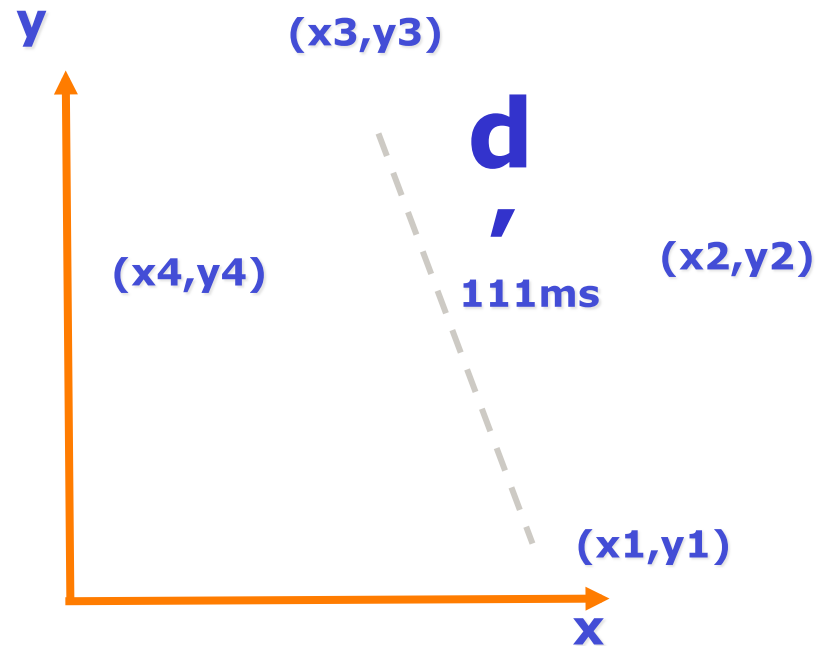
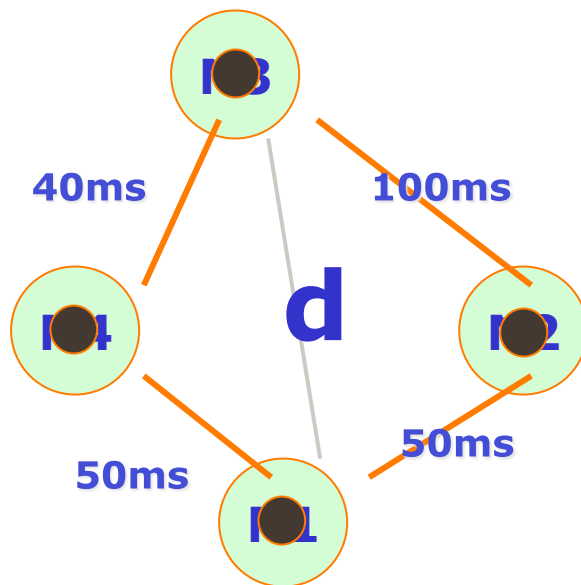
- Why studying Internet coordinate systems?
- How does an Internet coordinate system work?
  - Vivaldi
- Experimentation scenario
- Simulation scenario
- Our clustering algorithm
- Experimental results
- Conclusion and Future work

# Why studying Internet coordinate systems?

- Recently, a new approach has emerged for **Internet positioning** having the main advantage of providing estimates for **network delays** between machines at a **low measurement cost** (ICS).
- Can coordinates then be an efficient way for a **light-weight network diagnosis** that does not require the deployment of a **complex monitoring infrastructure**?

# How does an Internet coordinate system work?

- ICS (Internet Coordinate Systems):
  - Embed RTTs into geometric spaces
  - The network delay between any two nodes can be approximated by the geometric distance separating them.

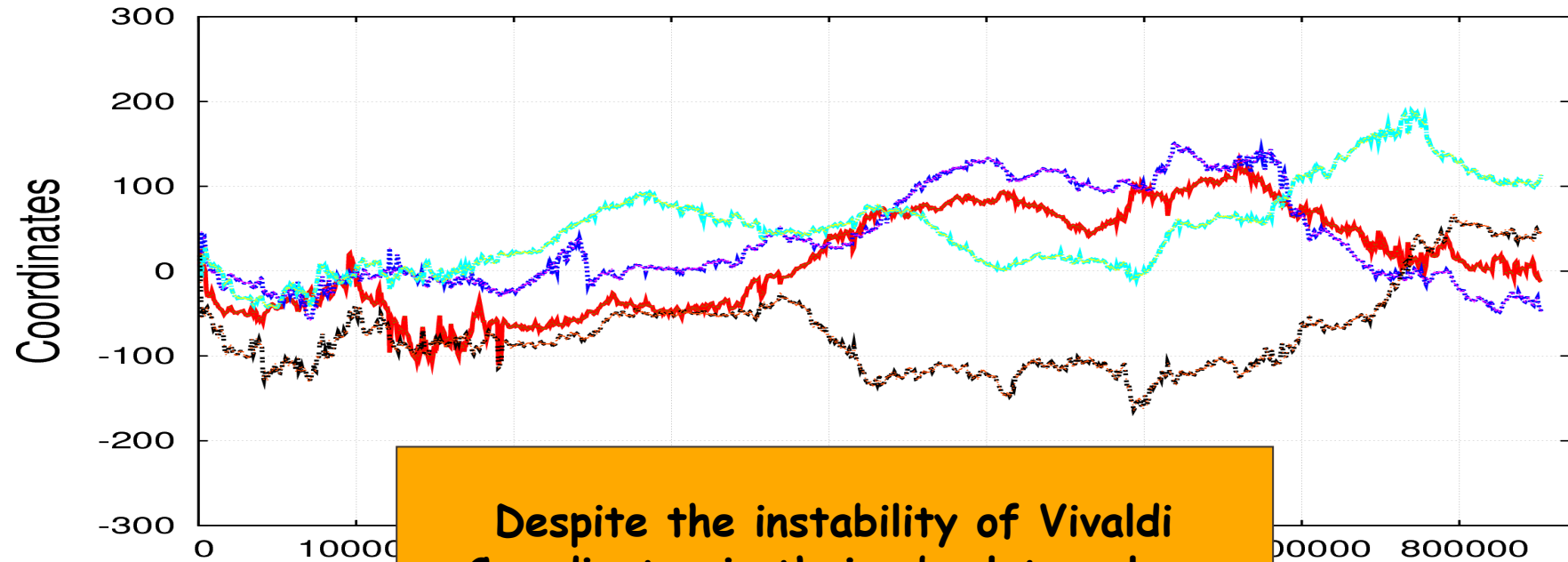


# Vivaldi : A decentralized Internet coordinate system

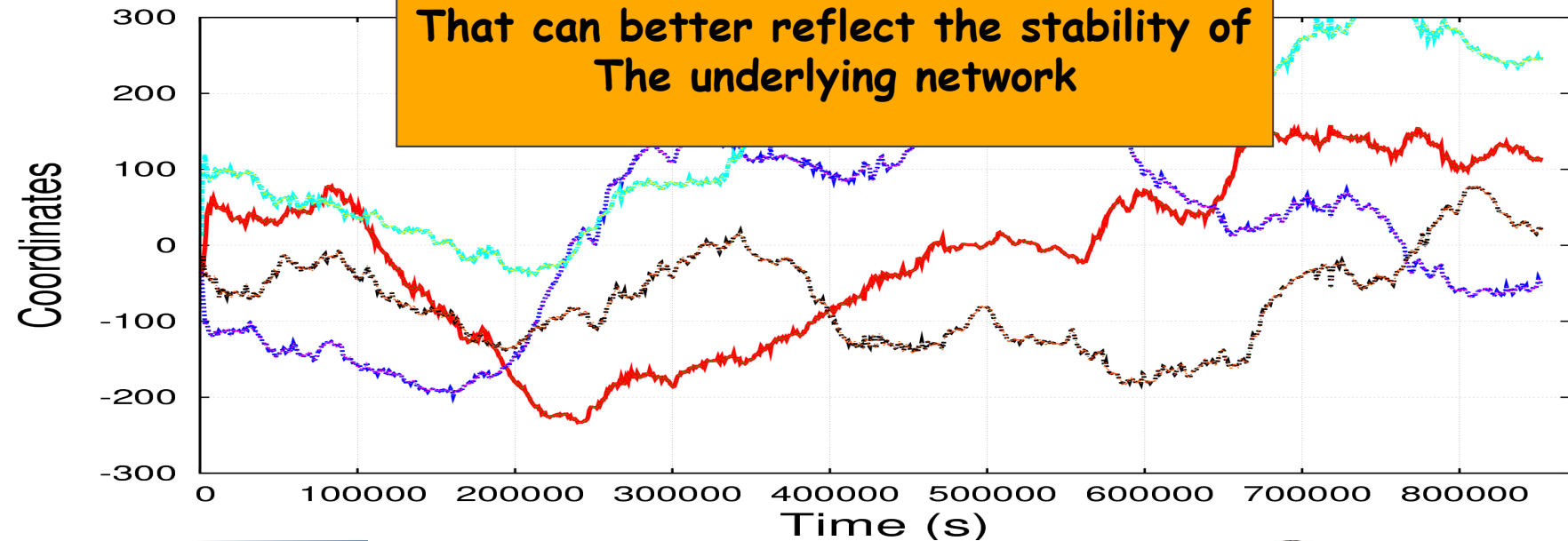
- Fully distributed, light-weight and efficient algorithm
- No fixed network infrastructure and no distinguished nodes.
- It is able to estimate network delays accurately while minimizing the load on the network.

# The basic idea of Vivaldi

- Every node has an estimation of its coordinate.
- It picks a random node and asks for its coordinate estimation.
- It computes the Euclidean distance between itself and this selected node and compare it to the network delay between them.
- It computes the stretch of the path and decides on the change to introduce into its coordinate.
- All nodes keep applying this algorithm in a decentralized manner until the whole system stabilizes.



Despite the instability of Vivaldi  
Coordinates in their absolute values  
There is still a stable internal structure  
That can better reflect the stability of  
The underlying network



# Experimentation scenario

- Pyxida implementation of Vivaldi (from Harvard, in java)
- 145 nodes
- 32 neighbors per node
- Four dimensions + height
- Applicative ping (UDP)
- One ping every 10 seconds
  - Approximately one tour every 320 seconds
- Measure coordinates every 10 seconds



# Simulation scenario

- For flexibility purposes, we also resort to simulations.
- To be close to reality, we simulate a **real topology** of PlanetLab provided by the iPlane infrastructure.
  - 200 nodes
- We fix the duration of all simulations to **30000** seconds as the convergence time of coordinates is around **2000** seconds.

# Clustering algorithm [1]

- **Cluster**: A set of nodes that are stable with respect to each other.
- $\epsilon$ : This is the threshold of allowed variations of Euclidean distances (expressed in ms).
- **Error** : an error occurs between two nodes  $i$  and  $j$  at time interval  $t$  when the shift of the Euclidean distance between them is larger than the threshold  $\epsilon$ .
- $C$ , or the confidence level, allows  $1-C$  distance error between two nodes.
- $I$ : Number of past time intervals of 10s to be considered for the clustering. After trying several values for  $I$ , we specify it to 100 in this work.

# Clustering algorithm [2]

- First, we calculate the **number of violations** from each node to all other.
- We sort nodes by their **decreasing number of violations**.
- The algorithm here starts with **all nodes in the same cluster**.
- To find the first cluster, we **exclude** the node with the **largest number of violations**, then we **recalculate** the number of violations for the remaining nodes. We continue excluding nodes with large number of violations **until there is no violation** between the nodes of the cluster.
- We **repeat the above steps** to form a **second cluster** with the excluded nodes.
- We **stop** the algorithm when we are left **without any excluded node**.

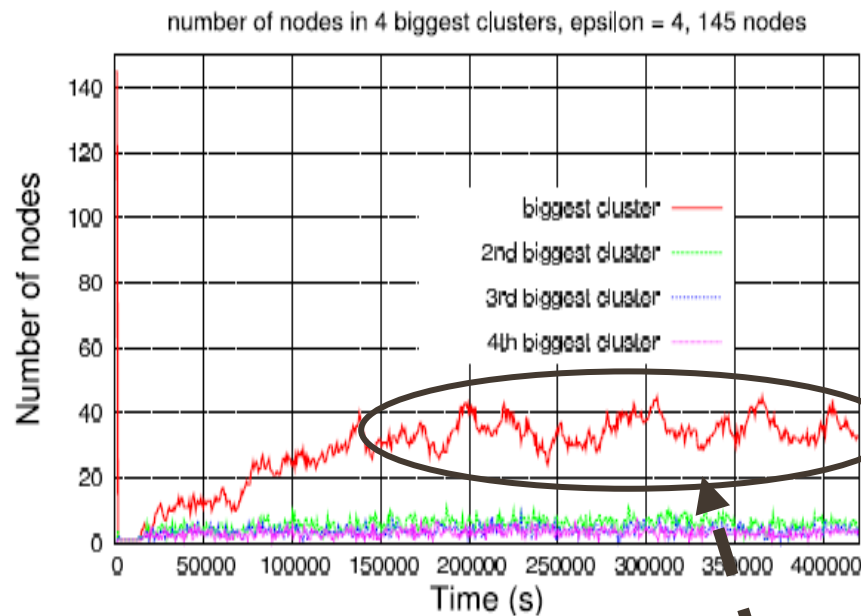


Fig.3(a) ( $\epsilon = 4\text{ms}$ )

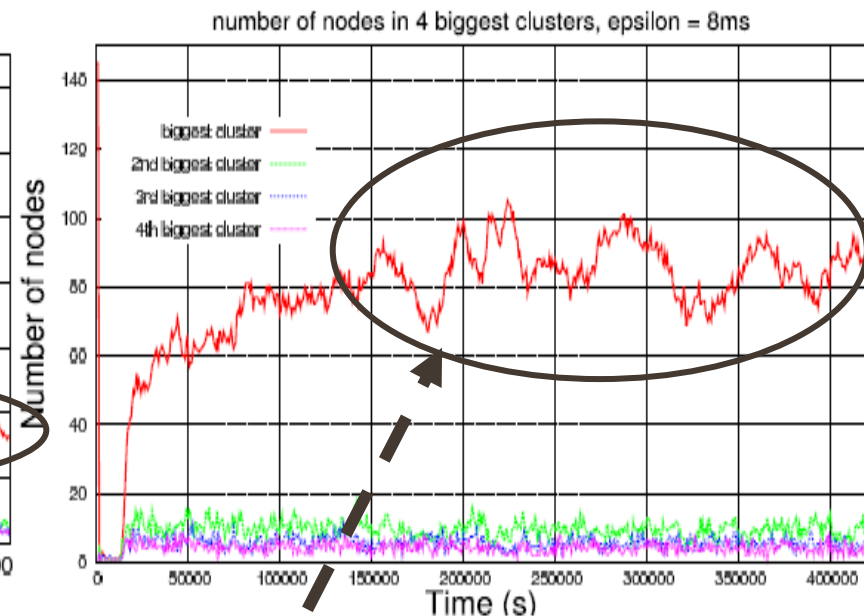


Fig.3(b) ( $\epsilon = 8\text{ms}$ )

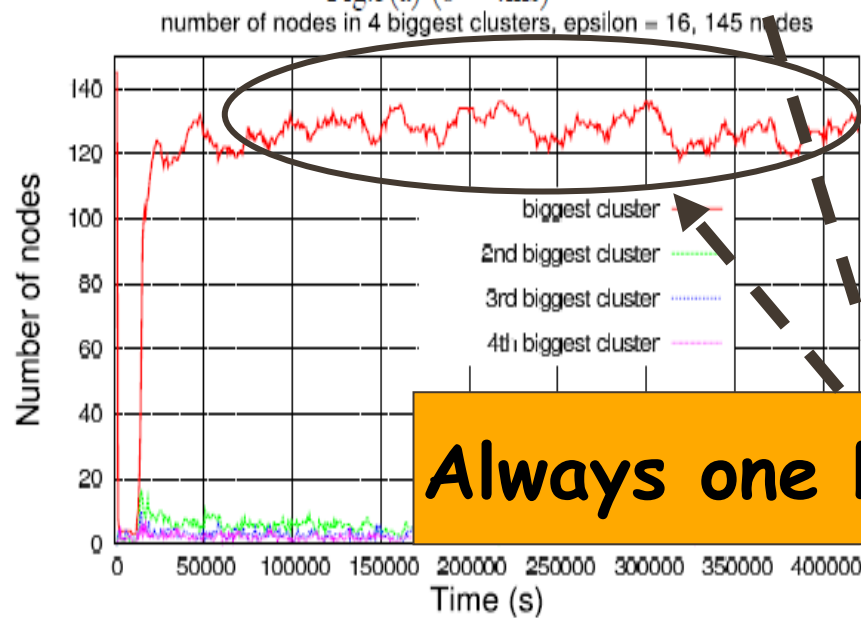


Fig.3(c) ( $\epsilon = 16\text{ms}$ )

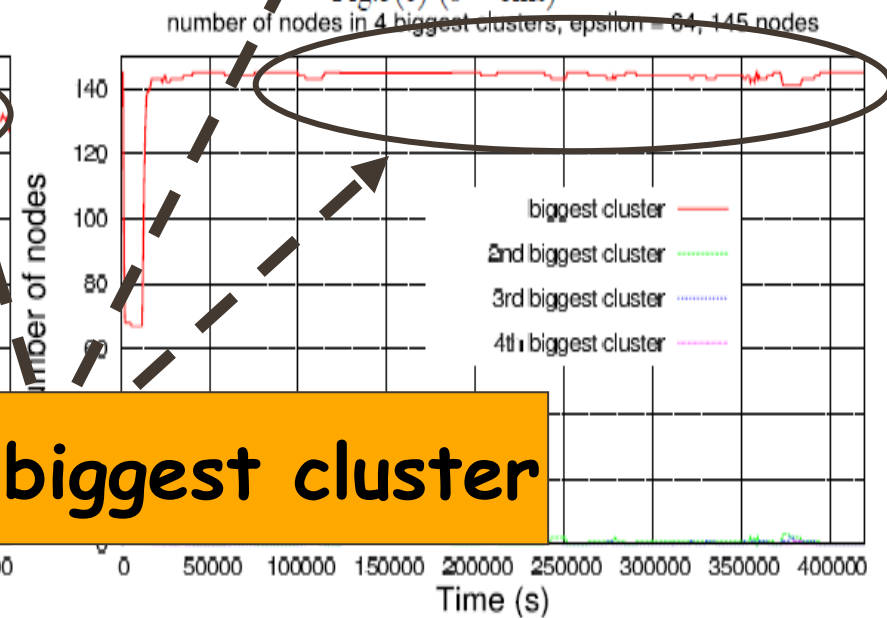
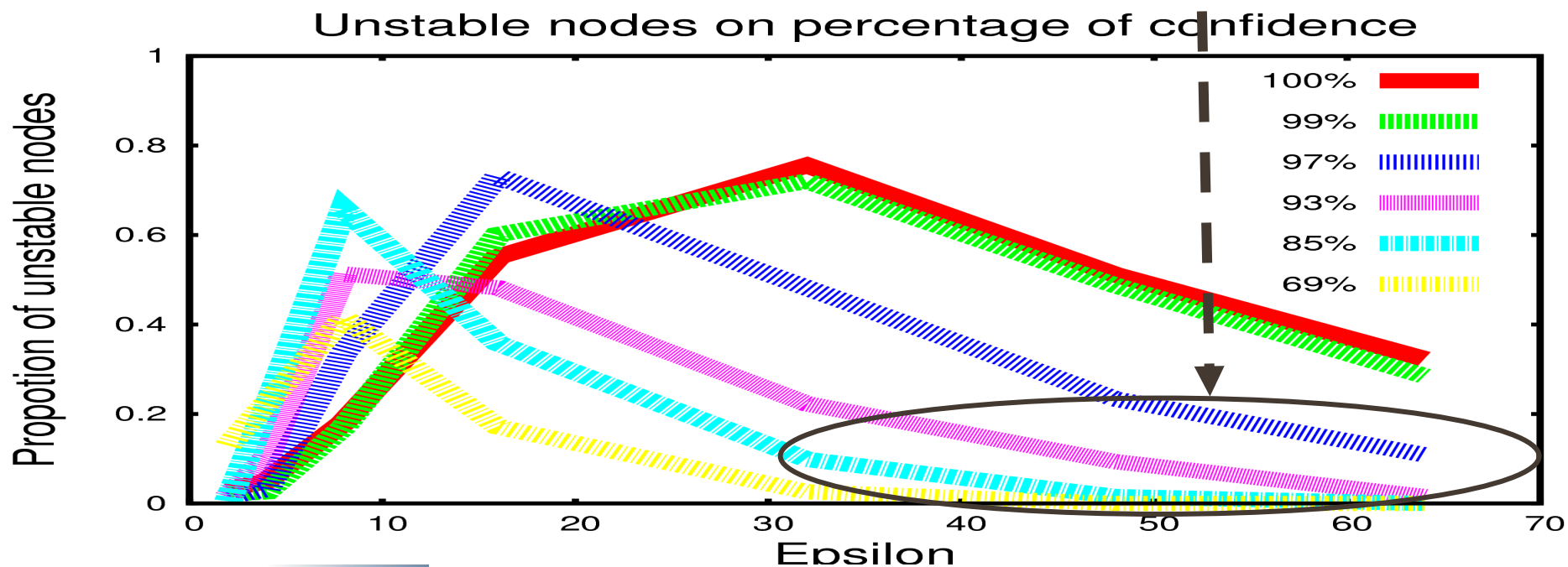
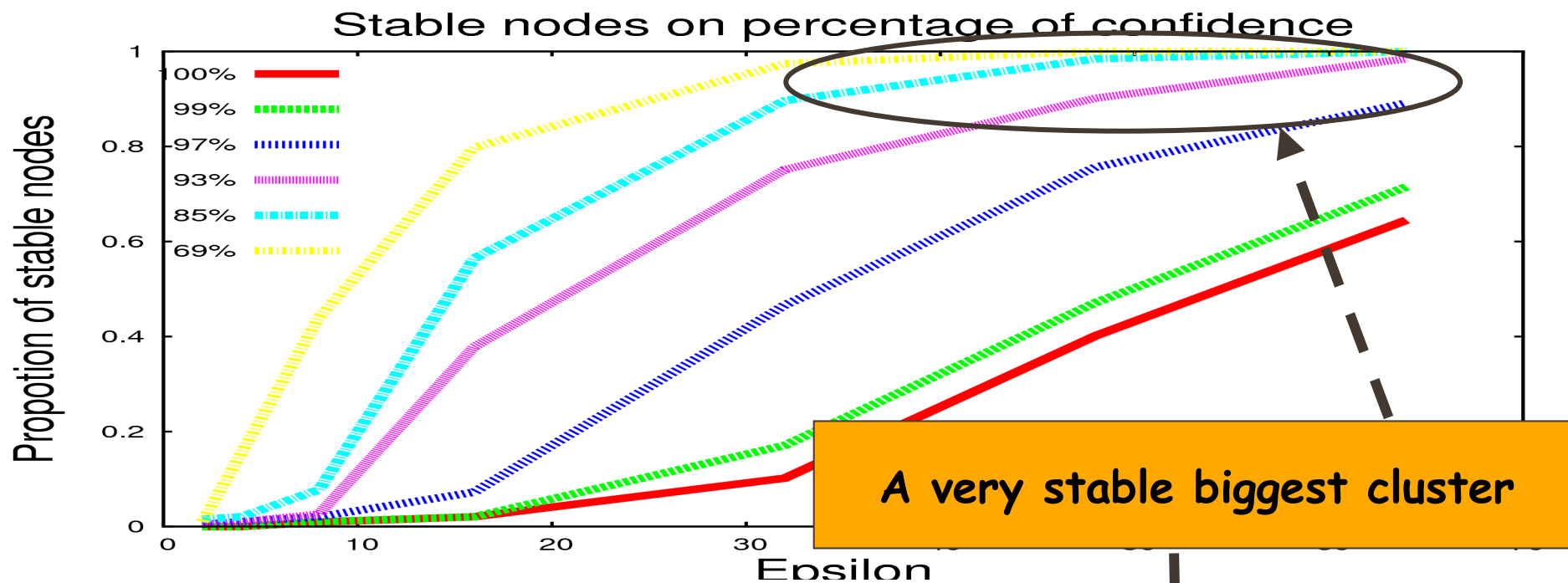
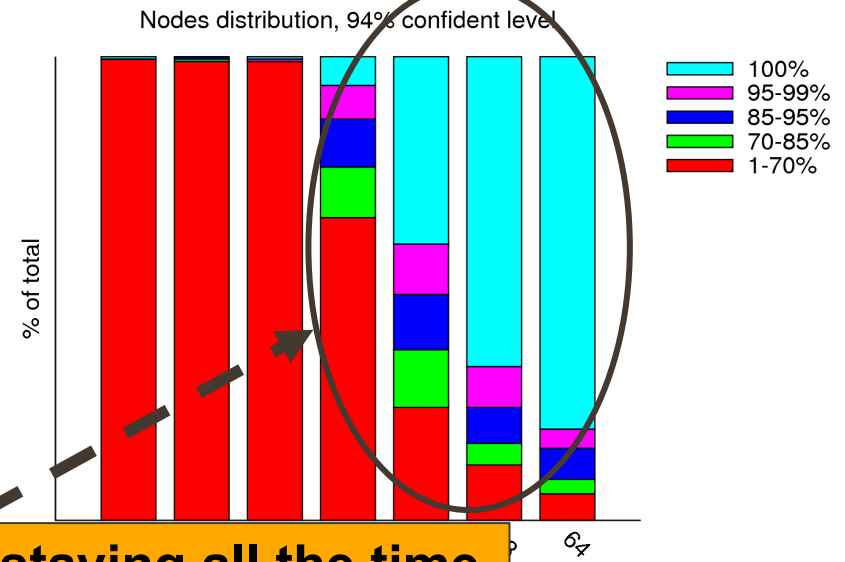
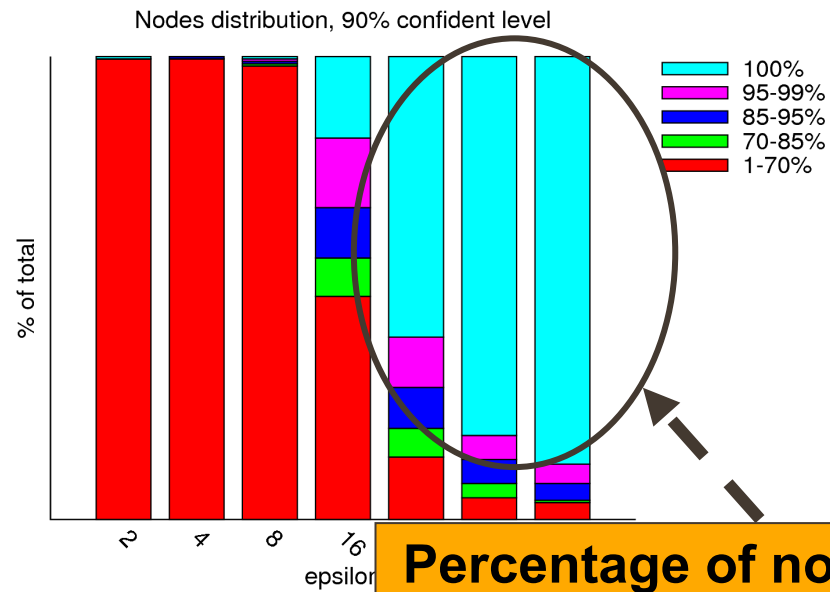


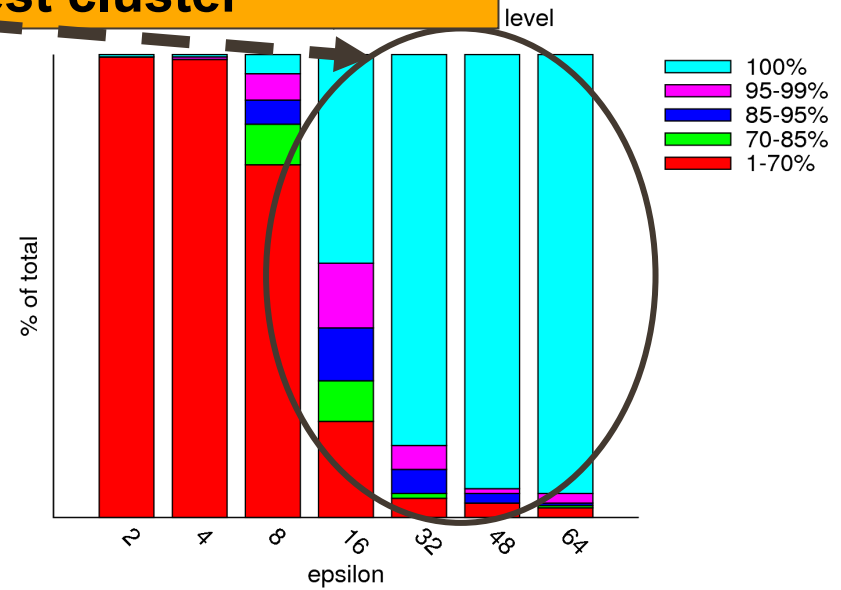
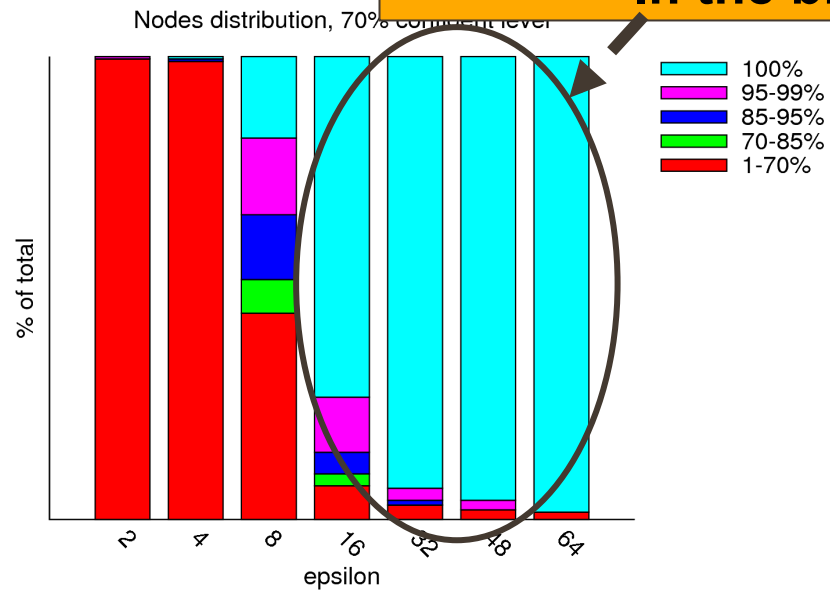
Fig.3(d) ( $\epsilon = 64\text{ms}$ )

**Always one biggest cluster**





**Percentage of node staying all the time  
In the biggest cluster**



# Conclusion

- We studied the **Vivaldi** coordinate system from inside and we showed that despite the **instability** of these coordinates, there is still a stable core of nodes that can be used to **track network changes**.
  - The **amount of changes** to detect and the **confidence level** of tracking can be set by the **network administrator**.
- We developed a **new clustering algorithm** that permitted us to group the **stable nodes** together following the **amount of variations** of their coordinates.

# Future work

- An **exhaustive experimental study** to validate the performance of such protocol by considering **a large set of scenarios** for changing network delays.
- Designing a **distributed protocol** for machine clustering and for **the detection and localization** of network delay anomalies, by the help of Vivaldi coordinates.



# Thank You

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